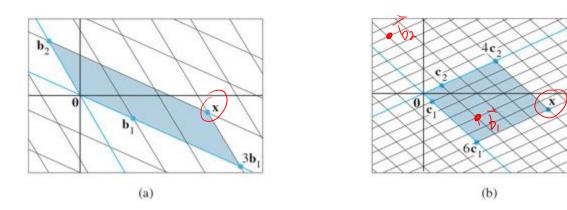
<u>4.7 – Change of Basis</u>

We are now going to look at converting a vector x in one coordinate system into another coordinate system – same vector, different coordinate representation.

Warnock - Class Notes

Consider the following vector spaces spanned by $\{\mathbf{b}_1, \mathbf{b}_2\}$ and $\{\mathbf{c}_1, \mathbf{c}_2\}$ respectively.



By observation, find $[\mathbf{x}]_B = 3\vec{b} + \vec{b}_a$ and $[\mathbf{x}]_C = 6\vec{c}_1 + 4\vec{c}_a$ = $\begin{bmatrix} 3\\ 2 \end{bmatrix}_B$

Ex 1: Consider two bases $B = \{\mathbf{b}_1, \mathbf{b}_2\}$ and $C = \{\mathbf{c}_1, \mathbf{c}_2\}$ for a vector space V, such that

$${f b}_1=4{f c}_1+{f c}_2 \ \ {
m and} \ \ {f b}_2=-6{f c}_1+{f c}_2$$

Suppose $\mathbf{x} = 3\mathbf{b}_1 + \mathbf{b}_2$ (that is, $[\mathbf{x}]_B = \begin{bmatrix} 3\\1 \end{bmatrix}$), find $[\mathbf{x}]_C$. $\begin{bmatrix} \vec{\chi} \end{bmatrix}_C = \begin{bmatrix} \vec{j} \cdot \vec{b}_1 + \vec{b}_2 \end{bmatrix}_C = 3\begin{bmatrix} \vec{b}_1 \end{bmatrix}_C + \begin{bmatrix} \vec{b}_2 \end{bmatrix}_C$ $= \begin{bmatrix} \vec{b}_1 \end{bmatrix}_C \begin{bmatrix} \vec{b}_2 \end{bmatrix}_C \begin{bmatrix} \vec{j}_1 \end{bmatrix}$ $= \begin{bmatrix} 4 & -6 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 7 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \end{bmatrix} = (\begin{bmatrix} \mathbf{x} \end{bmatrix}_C)$ $= \begin{bmatrix} \mathbf{x} \end{bmatrix}_C \begin{bmatrix} \mathbf{x} \end{bmatrix}_B = \begin{bmatrix} \mathbf{x} \end{bmatrix}_C$ Theorem 15 Let $B = {\mathbf{b}_1, \dots, \mathbf{b}_n}$ and $C = {\mathbf{c}_1, \dots, \mathbf{c}_n}$ be bases of a vector space V. Then there is a unique $n \times n$ matrix $\underset{C \leftarrow B}{P}$ such that

$$[\mathbf{x}]_C = \Pr_{C \leftarrow B} [\mathbf{x}]_B \tag{4}$$

The columns of $\underset{C \leftarrow B}{P}$ are the C-coordinate vectors of the vectors in the basis B. That is,

 $P_{C \leftarrow B} = [[\mathbf{b}_1]_C \quad [\mathbf{b}_2]_C \quad \dots \quad [\mathbf{b}_n]_C]$ (5)

$$P_{C+B} \text{ is the } \underline{hange} \quad \underline{of \ coordinates \ matrix \ from \ B \ to \ C}$$

$$(\mathbf{x}|_{C^{\bullet}} \underbrace{\mathbf{x}}_{\mathbf{x}} \underbrace{\mathbf{x}}_{\mathbf{x$$

$$(\underset{C\leftarrow B}{P})^{-1} = \underset{B\leftarrow C}{P}$$

Change of Basis in Rⁿ

If $B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ and ε is the standard basis $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$ in \mathbb{R}^n , then $[\mathbf{b}_1]_{\varepsilon} = \mathbf{b}_1$, and likewise for the other vectors in *B*. In this case, $\underset{\varepsilon \leftarrow B}{P}$ is the

same as the change-of-coordinates matrix $P_B\,$ introduced in Section 4.4, namely,

$$P_B = \begin{bmatrix} \mathbf{b}_1 & \mathbf{b}_2 & \cdots & \mathbf{b}_n \end{bmatrix}$$

However, to change coordinates between two non-standard bases in \mathbb{R}^n , we will need to use Theorem 5, and find coordinate vectors of the <u>old</u> <u>basis</u> relative to the <u>New</u> <u>basis</u>.

Ex 2:

Let
$$\mathbf{b}_{1} = \begin{bmatrix} -6 \\ -1 \end{bmatrix}$$
, $\mathbf{b}_{2} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$, $\mathbf{c}_{1} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$, $\mathbf{c}_{2} = \begin{bmatrix} 6 \\ -2 \end{bmatrix}$, and consider
the bases for \mathbb{R}^{2} given by $B = \{\mathbf{b}_{1}, \mathbf{b}_{2}\}$ and $C = \{\mathbf{c}_{1}, \mathbf{c}_{2}\}$. Find the
change-of-coordinates matrix from B to C.
 $\begin{bmatrix} \nabla \end{bmatrix}_{1} = \begin{bmatrix} C \\ -C \end{bmatrix} \begin{bmatrix} x \\ -C$