

<u>4.2 – Null Spaces, Column Spaces,</u> and Linear Transformations

Warnock - Class Notes

Remember that a homogeneous system of equations

$$5x_1 + 21x_2 + 19x_3 = 0$$

$$13x_1 + 23x_2 + 2x_3 = 0$$

$$8x_1 + 14x_2 + x_3 = 0$$

Can be written in matrix form as $A\mathbf{x} = \mathbf{0}$ where

	5	21	19	
A =	13	23	2	
	8	14	1	

The solution set is all the vectors \mathbf{x} that satisfy the matrix equation. We are going to name this set of solutions the <u>null</u> <u>space</u>.

Definition

The **null space** of an $m \times n$ matrix *A*, written as Nul *A*, is the set of all solutions of the homogeneous equation $A\mathbf{x} = \mathbf{0}$. In set notation,

$$\operatorname{Nul} A = \{ \mathbf{x} : \mathbf{x} ext{ is in } \mathbb{R}^n ext{ and } A\mathbf{x} = \mathbf{0} \}$$

Ex 1: Let A be the matrix defined above. Determine whether the vector $\mathbf{u} = \begin{vmatrix} -3 \\ -3 \\ 2 \end{vmatrix}$ belongs to the null space of A.

$$\begin{bmatrix} 5 & 2 & 1 & 19 \\ 13 & 23 & 2 \\ 8 & 14 & 1 \\ 2 \end{bmatrix} \begin{bmatrix} 5 \\ -3 \\ 2 \\ -3 \\ 2 \end{bmatrix} = \begin{bmatrix} 25 - 63 + 38 \\ 65 & -69 + 4 \\ 40 & -42 + 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \text{ yes!}$$



Theorem 2

The null space of an $m \times n$ matrix A is a subspace of \mathbb{R}^n . Equivalently, the set of all solutions to a system $A\mathbf{x} = \mathbf{0}$ of m homogeneous linear equations in n unknowns is a subspace of \mathbb{R}^n .

Proof: (1)
$$\vec{\partial} \in Nul A$$
, yes since $A\vec{o} = \vec{o}$
Let $\vec{u}, \vec{v} \in NulA$, $A\vec{u} = \vec{o}$, $A\vec{v} = \vec{o}$
(2) $A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v} = \vec{O} + \vec{o} = \vec{o} = \vec{v} \cdot \vec{u} + \vec{v} \in NulA$
(2) $A(\vec{u} + \vec{v}) = A\vec{u} = c \cdot \vec{o} = \vec{o} = \vec{v} \cdot c\vec{u} \in NulA$
(3) $A(c\vec{u}) = c A\vec{u} = c \cdot \vec{o} = \vec{o} = \vec{v} \cdot c\vec{u} \in NulA$
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Ex 2: Let H be the set of vectors in \mathbb{R}^3 whose coordinates a, b, and c satisfy the equations $\underline{\alpha - \lambda b} = 5c$ and $\underline{2q + 6b} = 7c$. Show that H is a subspace of \mathbb{R}^3 . (*Create 2 dependence relations between them.*)

 $\begin{array}{c} a - 2b - 5c = 0 \\ 2a + 6b - 7c = 0 \end{array} = \left[\begin{array}{c} 1 & -2 & -5 \\ 2 & 6 & -7 \end{array} \right] \left[\begin{array}{c} 4 \\ 6 \\ -7 \end{array} \right] = \left[\begin{array}{c} 0 \\ 0 \\ -7 \end{array} \right] \left[\begin{array}{c} 4 \\ -7 \end{array} \right] \left[\begin{array}{c} 4 \\ -7 \end{array} \right] \left[\begin{array}{c} 4 \\ -7 \end{array} \right] \left[\begin{array}{c} 0 \end{array} \\] \left[\begin{array}{c} 0 \end{array}$

Ex 3: Find a spanning set for the null space of the matrix $A = \begin{bmatrix} 1 & 3 & 5 & 0 \\ 0 & 1 & 4 & -2 \end{bmatrix} \cdot \frac{-3R_2 + R_1}{2}$

$$\begin{bmatrix} 1 & 0 & -7 & 6 \\ 0 & 1 & 4 & -2 \end{bmatrix} \xrightarrow{X_1 = 7_{X_3} - 6_{X_4}} \qquad \text{NulA} \in \mathbb{R}^{7} \\ X_2^{=} - 4_{X_3} + 2_{X_4} \\ \overrightarrow{X} = X_3 \begin{bmatrix} 7 \\ -4 \\ 1 \\ 0 \end{bmatrix} + X_4 \begin{bmatrix} -6 \\ 2 \\ 0 \\ 1 \end{bmatrix} \\ \boxed{0} \\ 1 \end{bmatrix} \\ \boxed{1} \\ \boxed{1} \\ \boxed{0} \\ 1 \end{bmatrix} \\ \boxed{1} \\ \boxed{1} \\ \boxed{1} \\ \boxed{0} \\ 1 \end{bmatrix} \\ \boxed{1} \\ \boxed{1}$$

Two properties of null spaces that contain nonzero vectors that we see from the last example.

- 1. The spanning set is automatically <u>linearly</u> independent
- 2. The number of vectors in the spanning set of Nul A is equal to the number of <u>Free</u> <u>Variables</u> in the equation $A\mathbf{x} = \mathbf{0}$.

Definition

The column space of an $m \times n$ matrix *A*, written as Col *A*, is the set of all linear combinations of the columns of *A*. If $A = [a_1 \cdots a_n]$, then

$$\operatorname{Col} A = \operatorname{Span} \{\mathbf{a}_1, \ldots, \mathbf{a}_n\}$$

Theorem 3

The column space of an m imes n matrix A is a subspace of \mathbb{R}^m .

$$\operatorname{Col} A = \{ \mathbf{b} : \mathbf{b} = A\mathbf{x} \text{ for some } \mathbf{x} \text{ in } \mathbb{R}^n \}$$

Ex 4: Find a matrix A such that $W = \operatorname{Col} A$.

$$\mathcal{W} = \left\{ \begin{bmatrix} b-c\\2b+c+d\\5c-4d\\d \end{bmatrix} : b,c,d \text{ real} \right\} \xrightarrow{\mathbf{A}} A = \begin{bmatrix} 1 & -1 & 0\\2 & 1 & 1\\0 & 5 & -4\\0 & 0 & 1 \end{bmatrix}$$
$$C \cap A = b \begin{bmatrix} 1\\2\\0\\0 \end{bmatrix} + c \begin{bmatrix} -1\\5\\0\\0 \end{bmatrix} + d \begin{bmatrix} 0\\-4\\1\\1 \end{bmatrix}$$

The column space of an $m \times n$ matrix A is all of \mathbb{R}^m if and only if the equation $A\mathbf{x} = \mathbf{b}$ has a solution for each \mathbf{b} in \mathbb{R}^m .



Contrast Between Nul A and Col A for an ${m m} imes {m n}$ Matrix A

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	Nul A	Col A		
	1. Nul A is a subspace of \mathbb{R}^n .	1 . Col A is a subspace of \mathbb{R}^m .		
	2. Nul <i>A</i> is implicitly defined; that is, you are given only a condition $(A\mathbf{x} = 0)$ that vectors in Nul <i>A</i> must satisfy.	2. Col A is explicitly defined; that is, you are told how to build vectors in Col A.		
	3. It takes time to find vectors in Nul <i>A</i> . Row operations on $\begin{bmatrix} A & 0 \end{bmatrix}$ are required.	3. It is easy to find vectors in Col <i>A</i> . The columns of <i>A</i> are displayed; others are formed from them.		
	4. There is no obvious relation between Nul <i>A</i> and the entries in <i>A</i> .	4. There is an obvious relation between Col A and the entries in A, since each column of A is in Col A.		
	5. A typical vector ${f v}$ in Nul A has the property $A{f v}={f 0}.$	5. A typical vector \mathbf{v} in Col A has the property that the equation $A\mathbf{x} = \mathbf{v}$ is consistent.		
	6. Given a specific vector v, it is easy to tell if v is in Nul A. Just compute A v.	6. Given a specific vector \mathbf{v} , it may take time to tell if \mathbf{v} is in Col A. Row operations on $\begin{bmatrix} A & \mathbf{v} \end{bmatrix}$ are required.		
Square	7. Nul $A = \{0\}$ if and only if the equation $A\mathbf{x} = 0$ has only the trivial solution.	7. Col $A = \mathbb{R}^m$ if and only if the equation $A\mathbf{x} = \mathbf{b}$ has a solution for every b in \mathbb{R}^m .		
	8. Nul $A = \{0\}$ if and only if the linear transformation $\mathbf{x} \mapsto A\mathbf{x}$ is one-to-one.	8. Col $A = \mathbb{R}^m$ if and only if the linear transformation $\mathbf{x} \mapsto A\mathbf{x}$ maps \mathbb{R}^n onto \mathbb{R}^m .		

Definition

A linear transformation T from a vector space V into a vector space W is a rule that assigns to each vector \mathbf{x} in V a unique vector $T(\mathbf{x})$ in W, such that

(i) $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$ for all \mathbf{u}, \mathbf{v} in V, and

(ii) $T(c\mathbf{u}) = cT(\mathbf{u})$ for all \mathbf{u} in V and all scalers c.

The null space of a linear transformation is called the <u>kernel</u>, such that $T(\mathbf{u}) = \mathbf{0}$.

The <u>range</u> of T is the set of all vectors in W of the form $T(\mathbf{x})$ for some $\mathbf{x} \in V$.

Range Т 0 h Kernel is a Range is a subspace of V subspace of W

Ex 6:

(Calculus required) Let V be the vector space of all real-valued functions f defined on an interval [a,b] with the property that they are differentiable and their derivatives are continuous functions on [a,b]. Let W be the vector space C[a,b] of all continuous functions on [a,b], and let $D: V \to W$ be the transformation that changes f in V into its derivative f'. In calculus, two simple differentiation rules are

$$D\left(f+g
ight)=D\left(f
ight)+D\left(g
ight) \quad ext{and} \quad D\left(cf
ight)=cD\left(f
ight)$$

That is, *D* is a linear transformation. It can be shown that the kernel of *D* is the set of constant functions on [a,b] and the range of *D* is the set *W* of all continuous functions on [a,b].

