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4.2 – Null Spaces, Column Spaces, Math 220 and Linear Transformations Warnock - Class Notes

Remember that a homogeneous system of equations

$$
5x_1 + 21x_2 + 19x_3 = 0
$$

$$
13x_1 + 23x_2 + 2x_3 = 0
$$

$$
8x_1 + 14x_2 + x_3 = 0
$$

Can be written in matrix form as $A{\bf x}{=}{\bf 0}$ where

The solution set is all the vectors **x** that satisfy the matrix equation. We are going to name this set of solutions the $\frac{n \times 1}{n}$ $\frac{5 \text{ p} \times 6}{n}$.

Definition

The null space of an $m \times n$ matrix A, written as Nul A, is the set of all solutions of the homogeneous equation $A\mathbf{x} = \mathbf{0}$. In set notation,

$$
\mathrm{Nul}\ A = \{\mathbf{x} : \mathbf{x} \text{ is in } \mathbb{R}^n \text{ and } A\mathbf{x} = \mathbf{0}\}
$$

3 2 $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ **Ex 1:** Let A be the matrix defined above. Determine whether the vector $|\mathbf{u} = |-3|$ $\left[\begin{array}{c} 2 \end{array}\right]$ belongs to the null space of A.

$$
\begin{bmatrix} 5 & 2 & | & | & 9 \\ 13 & 2 & 3 & | & 2 \\ 8 & 14 & 1 & | & 2 \end{bmatrix} \begin{bmatrix} 5 \\ -3 \\ 2 \end{bmatrix} = \begin{bmatrix} 25 - 63 + 38 \\ 65 - 69 + 4 \\ 40 - 42 + 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad y \in S.
$$

Theorem₂

The null space of an $m \times (n)$ matrix A is a subspace of \mathbb{R}^n . Equivalently, the set of all solutions to a system $A\mathbf{x} = \mathbf{0}$ of m homogeneous linear equations in *n* unknowns is a subspace of \mathbb{R}^n .

Proof:
$$
\bigcap_{i \in \mathbb{Z}} \overrightarrow{\partial} \in N_u
$$
 A , y_e 5 since $A\overrightarrow{\partial} = \overrightarrow{\partial}$
\nLet \overrightarrow{a} , $\overrightarrow{v} \in N_u$ $|A$, $A\overrightarrow{a} = \overrightarrow{\partial}$, $A\overrightarrow{v} = \overrightarrow{\partial}$
\n $(\partial) A(\overrightarrow{u} + \overrightarrow{v}) = A\overrightarrow{a} + A\overrightarrow{v} = \overrightarrow{\partial} + \overrightarrow{\partial} = \overrightarrow{\partial} = \overrightarrow{v}$ $\overrightarrow{u} + \overrightarrow{v} \in N_u$ $|A$
\n 3 $A(c\overrightarrow{u}) = c A\overrightarrow{u} = c \cdot \overrightarrow{\partial} = \overrightarrow{\partial} = \overrightarrow{v}$ $c\overrightarrow{u} \in N_u$ $|A$
\n \therefore N_u $|A$ \therefore a $subspace$ $\overrightarrow{\partial} \in \mathbb{R}$

Ex 2: Let H be the set of vectors in \mathbb{R}^3 whose coordinates a, b, and c satisfy the equations $a - \lambda b = 5c$ and $2a + 6b = 7c$.

Show that H is a subspace of \mathbb{R}^3 hat H is a subspace of \mathbb{R}^3 . (Create 2 dependence relations between them.)
 $2\alpha + b\beta - 7c = 0 \implies 2\alpha + b\beta - 7c =$ $H = NulA$

$$
= N_{ul}A
$$

$$
\therefore H \text{ is a subspace of } R^3
$$

Ex 3: Find a spanning set for the null space of the matrix $A = \begin{bmatrix} 1 & 3 & 5 & 0 \\ 0 & 1 & 4 & 6 \end{bmatrix}$ $A = \begin{vmatrix} 1 & 3 & 3 & 0 \\ 0 & 1 & 4 & -2 \end{vmatrix}$ $\begin{bmatrix} 1 & 3 & 5 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & 3 & 5 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix}$. $\begin{bmatrix} 0 & 1 & 4 & -2 \end{bmatrix}$ $=$ \overline{a} .

$$
\begin{bmatrix} 1 & 0 & -7 & 6 \\ 0 & 1 & 4 & -2 \end{bmatrix} \qquad \begin{array}{l} x_1 = 7x_3 - 6x_4 \\ x_2 = -4x_3 + 2x_4 \end{array}
$$
\n
$$
\overrightarrow{\chi} = x_3 \begin{bmatrix} 7 \\ -4 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -6 \\ 2 \\ 0 \end{bmatrix}
$$
\n
$$
\begin{array}{l} x_1 = x_3 \begin{bmatrix} 7 \\ -4 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -6 \\ 2 \\ 0 \end{bmatrix} \end{array}
$$
\n
$$
\begin{array}{l} x_1 = x_3 \begin{bmatrix} 7 \\ -4 \\ 0 \end{bmatrix} \begin{bmatrix} -6 \\ 2 \\ 0 \end{bmatrix} \end{array}
$$

Two properties of null spaces that contain nonzero vectors that we see from the last example.

- 1. The spanning set is automatically ___________________ ________________
- 2. The number of vectors in the spanning set of Nul A is equal to the number of $\frac{1}{2}$ *i* e *y ar i* α ble 5 in the equation A **x**=0.

Definition

The column space of an $m \times n$ matrix A, written as Col A, is the set of all linear combinations of the columns of A. If $A = [\boldsymbol{a}_1 \quad \cdots \quad \boldsymbol{a}_n]$, then

$$
\mathrm{Col}\:A=\mathrm{Span}\,\{\mathbf{a}_1,\ldots,\mathbf{a}_n\}
$$

Theorem 3

The column space of an $m \times n$ matrix A is a subspace of \mathbb{R}^m .

$$
\operatorname{Col} A = \{ \mathbf{b} : \mathbf{b} = A\mathbf{x} \text{ for some } \mathbf{x} \text{ in } \mathbb{R}^n \}
$$

Ex 4: Find a matrix A such that $W = \text{Col}A$.

$$
\mathbf{W} = \left\{ \begin{bmatrix} b-c \\ 2b+c+d \\ 5c-4d \\ d \end{bmatrix} : b, c, d \text{ real} \right\} \text{ for } \mathbf{A} = \begin{bmatrix} 1 & -1 & 0 \\ 2 & 1 & 1 \\ 0 & 5 & -4 \\ 0 & 0 & 1 \end{bmatrix}
$$

$$
C \circ | A = b \begin{bmatrix} 1 & -1 & 0 \\ 2 & 1 & 1 \\ 0 & 5 & -4 \\ 0 & 0 & 1 \end{bmatrix} + c \begin{bmatrix} -1 \\ 1 \\ 5 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 1 \\ -4 \\ 1 \end{bmatrix}
$$

The column space of an $m \times n$ matrix A is all of \mathbb{R}^m if and only if the equation $A\mathbf{x} = \mathbf{b}$ has a solution for each **b** in \mathbb{R}^m .

Contrast Between Nul A and Col A for an $m \times n$. Matrix A

Definition

A linear transformation T from a vector space V into a vector space W is a rule that assigns to each vector x in V a unique vector $T(x)$ in W, such that

(i) $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$ for all \mathbf{u} , \mathbf{v} in V , and

(ii) $T(c\mathbf{u}) = cT(\mathbf{u})$ for all **u** in V and all scalers c.

The null space of a linear transformation is called the $\frac{1}{\sqrt{e}}$ $\frac{1}{\sqrt{e}}$, such that $T(\mathbf{u}) = \mathbf{0}$.

The $\sqrt{a \wedge g}$ of T is the set of all vectors in W of the form $T(\mathbf{x})$ for some $\mathbf{x} \in V$.

Range Т $\bf{0}$ h Kernel is a
subspace of V Range is a
subspace of W

Square

Ex 6:

(Calculus required) Let V be the vector space of all real-valued functions f defined on an interval $[a, b]$ with the property that they are differentiable and their derivatives are continuous functions on [a, b]. Let W be the vector space $C[a,b]$ of all continuous functions on [a, b], and let $\overline{D}:V\rightarrow W$ be the transformation that changes f in V into its derivative f' . In calculus, two simple differentiation rules are

$$
D(f+g)=D\left(f\right)+D\left(g\right)\quad\text{and}\quad D\left(cf\right)=cD\left(f\right)
$$

That is, D is a linear transformation. It can be shown that the kernel of D is the set of constant functions on $[a,b]$ and the range of D is the set W of all continuous functions on $[a,b]$.

