

## 4.1 – Preliminary Theory – Linear Equations

An  $n^{\text{th}}$ -order linear Initial Value Problem has the form

$$\text{Solve: } a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \dots + a_0(x)y = g(x)$$

$$\text{Subject to: } y(x_0) = y_0, y'(x_0) = y_1, \dots, y^{(n-1)}(x_0) = y_{n-1}$$

The solution  $y(x)$  must

a) pass through  $(x_0, y_0)$

b) have slope  $y_1$  at  $(x_0, y_0)$

c) have concavity  $y_2$  at  $(x_0, y_0)$

etc.

### THEOREM 4.1.1 Existence of a Unique Solution

Let  $a_n(x), a_{n-1}(x), \dots, a_1(x), a_0(x)$  and  $g(x)$  be continuous on an interval  $I$  and let  $a_n(x) \neq 0$  for every  $x$  in this interval. If  $x = x_0$  is any point in this interval, then a solution  $y(x)$  of the initial-value problem (1) exists on the interval and is unique.

$y = 3e^{2x} + e^{-2x} - 3x$  is a solution to  $y'' - 4y = 12x$ ,  $y(0) = 4$ ,  $y'(0) = 1$ . ↖  $6e^0 - 2e^0 - 3$

We know that it's unique because  $a_2(x) = 1 \neq 0$  on any interval containing  $x = 0$ .

$y = cx^2 + x + 3$  is a solution to  $x^2y'' - 2xy' + 2y = 6$ ,  $y(0) = 3$ ,  $y'(0) = 1$  for ANY  $c$ .

This is not unique, because  $a_2(x) = x^2 = 0$  at  $x = 0$ .

A 2<sup>nd</sup>-order boundary - value problem (BVP) has the form

Solve:  $a_2(x)y'' + a_1(x)y' + a_0(x)y = g(x)$

Subject to:  $y(a) = y_0, y(b) = y_1$

These are called boundary conditions.

There many possible pairs of boundary conditions.

A BVP could have one solution, no solutions, or many solutions.

$y'(a) = y_0,$	$y(b) = y_1$
$y(a) = y_0,$	$y'(b) = y_1$
$y'(a) = y_0,$	$y'(b) = y_1,$

**Ex #1.** Given that  $y = c_1 \sin(6x) + c_2 \cos(6x)$  is a 2-parameter family of solutions to the DE  $y'' + 36y = 0$ , find the solutions with the boundary conditions:

a)  $y(0) = 0, y\left(\frac{\pi}{2}\right) = 0$

$0 = c_1 \cdot \sin 0 + c_2 \cos 0 \Rightarrow 0 = c_2$

$0 = c_1 \sin 3\pi + c_2 \cos 3\pi \Rightarrow 0 = -c_2$

$c_1$  is arbitrary

$y = c_1 \sin 6x$  (infinite solutions)

b)  $y(0) = 0, y\left(\frac{\pi}{2}\right) = 1$

$c_2 = 0$

$1 = c_1 \sin 3\pi + c_2 \cos 3\pi$

$1 = -c_2 \Rightarrow c_2 = -1$

Contradiction  $\rightarrow$  no solution

c)  $y(0) = 0, y\left(\frac{\pi}{4}\right) = 1$   $1 = c_1 \sin \frac{3\pi}{2} + c_2 \cos \frac{3\pi}{2}$

$c_2 = 0$

$1 = c_1 \cdot (-1)$

$c_1 = -1$

$y = -\sin 6x$

A homogeneous DE has the form

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \dots + a_0(x)y = 0$$

Whereas, a non homogeneous DE has the form

$$\underbrace{a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \dots + a_0(x)y}_{L(y)} = g(x)$$

To solve a non-homogeneous DE, we will first solve the associated homogeneous DE.

**Assumptions: (for simplicity)**

a)  $a_i(x)$ ,  $i=0,1,2,\dots,n$  and  $g(x)$  are continuous

b)  $a_n(x) \neq 0$  for every  $x$  in the interval

$D$  is called a differential operator.

$$D(y) = y' = \frac{dy}{dx}$$

$$D(D(y)) = D(y') = y'' \text{ - We can also say } D^2(y) = y'' \text{ and } D^n(y) = y^{(n)}$$

**An  $n$ th-order Differential Operator is**

$$L = a_n(x)D^n + \dots + a_1(x)D + a_0(x)$$

$$L(y) = a_n(x)y^{(n)} + \dots + a_1(x)y' + a_0(x)y$$

**$L$  is linear, so**

$$L(y_1 + y_2) = L(y_1) + L(y_2)$$

$$L(cy) = cL(y)$$

Therefore,  $y$  is a solution to the homogeneous DE if

$$L(y) = a_n(x)y^{(n)} + \dots + a_1(x)y' + a_0(x)y = 0$$

$$L(y) = 0$$

**Theorem 4.1.2: Superposition Principle – Homogeneous Equations**

Let  $y_1, y_2, \dots, y_k$  be solutions of the homogeneous  $n$ th-order DE

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \dots + a_0(x)y = 0$$

on an interval  $I$ . Then the linear combination

$$y = c_1 y_1(x) + c_2 y_2(x) + \dots + c_k y_k(x)$$

where the  $c_i, i=1, 2, \dots, k$  are arbitrary constants, is also a solution on the interval.

*solutions of  $L(y) = 0$*

Proof:

Let  $y = c_1 y_1(x) + c_2 y_2(x) + \dots + c_k y_k(x)$  ( $c_i$  are arbitrary constants)

$$L(y) = L(c_1 y_1(x) + c_2 y_2(x) + \dots + c_k y_k(x))$$

$$= c_1 L(y_1(x)) + c_2 L(y_2(x)) + \dots + c_k L(y_k(x))$$

$$= c_1 \cdot 0 + c_2 \cdot 0 + \dots + c_k \cdot 0 \quad (y_1 - y_k \text{ are solutions of } L(y) = 0)$$

$$= 0 \quad \therefore y \text{ is a solution to } L(y) = 0$$

*Lemma comes before*

**COROLLARIES TO THEOREM 4.1.2**

(A) A constant multiple  $y = c_1 y_1(x)$  of a solution  $y_1(x)$  of a homogeneous linear differential equation is also a solution.

(B) A homogeneous linear differential equation always possesses the trivial solution  $y = 0$ .

**Ex #1.**  $y_1 = x^2$  and  $y_2 = x^2 \ln x$  are both solutions to  $x^3 y''' - 2xy' + 4y = 0$  on the interval  $(0, \infty)$ . By the superposition principle,

$$y = c_1 x^2 + c_2 x^2 \ln x$$

is also a solution.

$$\begin{aligned} y_1 &= x^2 \\ y_1' &= 2x \\ y_1'' &= 2 \\ y_1''' &= 0 \end{aligned}$$

$$y_2' = 2x \ln x + x$$

$$y_2'' = 2 \ln x + 2 + 1$$

$$y_2''' = \frac{2}{x}$$

$$x^3 \cdot \frac{2}{x} - 2x(2x \ln x + x) + 4(x^2 \ln x)$$

$$2x^2 - 4x^2 \ln x - 2x^2 + 4x^2 \ln x = 0 \quad \checkmark$$

$$- 2x \cdot 2x + 4x^2 = 0 \quad \checkmark$$

### DEFINITION 4.1.1 Linear Dependence/Independence

A set of functions  $f_1(x), f_2(x), \dots, f_n(x)$  is said to be **linearly dependent** on an interval  $I$  if there exist constants  $c_1, c_2, \dots, c_n$ , not all zero, such that

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0$$

for every  $x$  in the interval. If the set of functions is not linearly dependent on the interval, it is said to be **linearly independent**.

In other words, a set of functions is linearly independent if the **ONLY** constants for

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0$$

are  $c_1 = c_2 = \dots = c_n = 0$

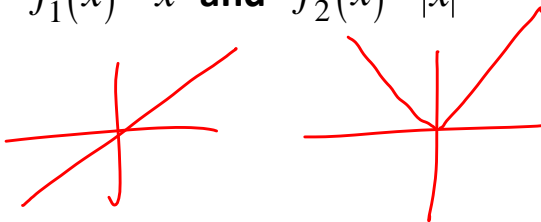
Linear dependence for two functions simply means one can be written as a constant multiple of the other.

**Examples:**

$$f_1(x) = \sin(2x) \text{ and } f_2(x) = \sin x \cos x$$

$$\left. \begin{aligned} f_1(x) &= \sin(2x) = 2 \sin x \cos x \\ &= 2 f_2(x) \\ f_1(x) - 2 f_2(x) &= 0 \end{aligned} \right\} f_1 \text{ \& } f_2 \text{ are linearly dependent}$$

$$f_1(x) = x \text{ and } f_2(x) = |x|$$



$$c_1 x + c_2 |x| = 0$$

$c_1 = c_2 = 0$  is the only solution

**Ex #2.** Show  $y_1 = x$  and  $y_2 = x^2$  are linearly independent on  $(-2, 2)$ .

Suppose  $C_1 x + C_2 x^2 = 0$

If  $x = 1$   $C_1 + C_2 = 0$   
 $C_1 = -C_2$

If  $x = -1$   $-C_1 + C_2 = 0$   
 $C_2 = C_1$

$C_2 = -C_2$   
 $2C_2 = 0$   
 $C_2 = 0 = C_1$

$\therefore$  linearly independent

**Ex #3.** Show that  $y_1 = \cos^2 x$ ,  $y_2 = \sin^2 x$ ,  $y_3 = \sec^2 x$ ,  $y_4 = \tan^2 x$  are linearly dependent on  $\left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$ .

$C_1 \cos^2 x + C_2 \sin^2 x + C_3 \sec^2 x + C_4 \tan^2 x = 0$

Let  $C_1 = 1$   
 $C_2 = 1$   
 $C_3 = -1$   
 $C_4 = 1$

$\cos^2 x + \sin^2 x - \sec^2 x + \tan^2 x$   
 $\quad \quad \quad 1 \quad -1$   
 $= 0$

$\therefore$  linearly dependent

$\frac{\sin^2 x + \cos^2 x}{\cos^2 x} = \frac{1}{\cos^2 x}$   
 $\tan^2 x + 1 = \sec^2 x$   
 $\tan^2 x - \sec^2 x = -1$

#### DEFINITION 4.1.2 Wronskian

Suppose each of the functions  $f_1(x), f_2(x), \dots, f_n(x)$  possesses at least  $n - 1$  derivatives. The determinant

$$W(f_1, f_2, \dots, f_n) = \begin{vmatrix} f_1 & f_2 & \cdots & f_n \\ f_1' & f_2' & \cdots & f_n' \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & \cdots & f_n^{(n-1)} \end{vmatrix},$$

where the primes denote derivatives, is called the **Wronskian** of the functions.

$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

$\begin{vmatrix} a & -b & c \\ d & e & -f \\ g & -h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \dots + a_0(x)y = 0 \quad (6)$$

### THEOREM 4.1.3 Criterion for Linearly Independent Solutions

Let  $y_1, y_2, \dots, y_n$  be  $n$  solutions of the homogeneous linear  $n$ th-order differential equation (6) on an interval  $I$ . Then the set of solutions is **linearly independent** on  $I$  if and only if  $W(y_1, y_2, \dots, y_n) \neq 0$  for every  $x$  in the interval.

So, when  $y_1, y_2, \dots, y_n$  are solutions on  $I$ ,  $W(y_1, y_2, \dots, y_n)$  is either

- identically zero (linearly dependent solution), or
- never zero on the interval (linearly independent solution)

### DEFINITION 4.1.3 Fundamental Set of Solutions

Any set  $y_1, y_2, \dots, y_n$  of  $n$  linearly independent solutions of the homogeneous linear  $n$ th-order differential equation (6) on an interval  $I$  is said to be a **fundamental set of solutions** on the interval.

### THEOREM 4.1.4 Existence of a Fundamental Set

There exists a fundamental set of solutions for the homogeneous linear  $n$ th-order differential equation (6) on an interval  $I$ .

### THEOREM 4.1.5 General Solution—Homogeneous Equations

Let  $y_1, y_2, \dots, y_n$  be a fundamental set of solutions of the homogeneous linear  $n$ th-order differential equation (6) on an interval  $I$ . Then the **general solution** of the equation on the interval is

$$y = c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x),$$

where  $c_i, i = 1, 2, \dots, n$  are arbitrary constants.

**Ex #4.** Use the Wronskian to determine whether the following solutions are linearly independent or linearly dependent. Assume they are solutions.

a)  $y_1 = \cos(2x)$ ,  $y_2 = \sin(2x)$  for  $y'' + 4y = 0$ .

$$\begin{vmatrix} \cos(2x) & \sin(2x) \\ -2\sin(2x) & 2\cos(2x) \end{vmatrix} = 2\cos^2(2x) - (-2\sin^2(2x)) \\ = 2(\cos^2(2x) + \sin^2(2x)) \\ = 2 \cdot 1 = 2 \neq 0 \\ \therefore \text{linearly independent}$$

$$y = C_1 \cos(2x) + C_2 \sin(2x)$$

$$e^{2x} e^{-x} = e^x$$

b)  $y_1 = e^x$ ,  $y_2 = e^{2x}$ ,  $y_3 = e^{-x}$  for  $y''' - 2y'' - y' + 2y = 0$ .

$$\begin{vmatrix} e^x & e^{2x} & e^{-x} \\ -e^x & 2e^{2x} & -e^{-x} \\ e^x & 4e^{2x} & e^{-x} \end{vmatrix} = e^x \begin{vmatrix} 2e^{2x} & -e^{-x} \\ 4e^{2x} & e^{-x} \end{vmatrix} - e^x \begin{vmatrix} e^{2x} & e^{-x} \\ 4e^{2x} & e^{-x} \end{vmatrix} + e^x \begin{vmatrix} e^{2x} & e^{-x} \\ 2e^{2x} & -e^{-x} \end{vmatrix} \\ = e^x [2e^x + 4e^x - e^x + 4e^x + -e^x - 2e^x] \\ = e^x \cdot 6e^x = 6e^{2x} \neq 0 \therefore \text{linearly independent}$$

c)  $y_1 = 5$ ,  $y_2 = \cos^2 x$ ,  $y_3 = \sin^2 x$

$$\begin{vmatrix} 5 & \cos^2 x & \sin^2 x \\ 0 & -2\cos x \sin x & 2\sin x \cos x \\ 0 & -2\cos 2x & 2\cos 2x \end{vmatrix} = 5 \cdot \begin{vmatrix} -\sin 2x & \sin 2x \\ 2\cos 2x & 2\cos 2x \end{vmatrix} + 0 + 0 \\ = 5(-2\sin 2x \cos 2x + 2\sin 2x \cos 2x) \\ = 5 \cdot 0 = 0 \therefore \text{linearly dependent}$$



$$3x + 7y > 2$$

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \dots + a_0(x)y = g(x) \quad (7)$$

### THEOREM 4.1.6 General Solution—Nonhomogeneous Equations

Let  $y_p$  be any particular solution of the nonhomogeneous linear  $n$ th-order differential equation (7) on an interval  $I$ , and let  $y_1, y_2, \dots, y_n$  be a fundamental set of solutions of the associated homogeneous differential equation (6) on  $I$ . Then the **general solution** of the equation on the interval is

$$y = c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x) + y_p,$$

where the  $c_i, i = 1, 2, \dots, n$  are arbitrary constants.

$y_p$  here is a particular solution free of arbitrary parameters.

For example,  $y_p = 3$  is a particular solution of  $y'' + 9y = 27$

Proof: Let  $Y(x) \neq y_p(x)$  be any particular solution of  $\uparrow$   
 $L(y) = g(x)$   
 Call  $u(x) = Y(x) - y_p(x)$

$$L(u) = L(Y - y_p) = L(Y) - L(y_p) = g(x) - g(x) = 0$$

$u$  is a solution to the homogeneous  $L(y) = 0$

$$u = c_1 y_1 + c_2 y_2 + \dots + c_n y_n$$

$$Y(x) = u(x) + y_p(x) = c_1 y_1 + c_2 y_2 + \dots + c_n y_n + y_p$$

So the general solution of a nonhomogeneous linear equation consists of two functions:  $y = c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x) + y_p(x) \equiv y_c(x) + y_p(x)$ .

$y_c(x)$  is called the complementary function.

**THEOREM 4.1.7 Superposition Principle—Nonhomogeneous Equations**

Let  $y_{p_1}, y_{p_2}, \dots, y_{p_k}$  be  $k$  particular solutions of the nonhomogeneous linear  $n$ th-order differential equation (7) on an interval  $I$  corresponding, in turn, to  $k$  distinct functions  $g_1, g_2, \dots, g_k$ . That is, suppose  $y_{p_i}$  denotes a particular solution of the corresponding differential equation

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y = g_i(x), \quad (12)$$

where  $i = 1, 2, \dots, k$ . Then

$$y_p = y_{p_1}(x) + y_{p_2}(x) + \cdots + y_{p_k}(x) \quad (13)$$

is a particular solution of

$$\begin{aligned} a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y \\ = g_1(x) + g_2(x) + \cdots + g_k(x). \end{aligned} \quad (14)$$

35. (a) Verify that  $y_{p_1} = 3e^{2x}$  and  $y_{p_2} = x^2 + 3x$  are, respectively, particular solutions of

(time-permitting)

$$y'' - 6y' + 5y = -9e^{2x}$$

$$\text{and } y'' - 6y' + 5y = 5x^2 + 3x - 16.$$

- (b) Use part (a) to find particular solutions of

$$y'' - 6y' + 5y = 5x^2 + 3x - 16 - 9e^{2x}$$

$$\text{and } y'' - 6y' + 5y = -10x^2 - 6x + 32 + e^{2x}.$$

$$y'' - 6y' + 5y = 2(5x^2 + 3x - 16) - \frac{1}{9}(-9e^{2x})$$

$$y_p = -2(x^2 + 3x) - \frac{1}{9}(3e^{2x})$$

$$y_p = -2x^2 - 6x - \frac{1}{3}e^{2x}$$