

100	90's	80's	70's	60's	< 60
2	10	7	14	9	7

Assessment 3 (10 or 11 am)
Dusty Wilson
Math 220

Name (first & last): Key

No work = no credit

$$\bar{X} = 75.67$$

$$\text{med} = 75$$

Biographical history, as taught in our public schools, is still largely a history of boneheads: ridiculous kings and queens, paranoid political leaders, compulsive voyagers, ignorant generals -- the flotsam and jetsam of historical currents. The men who radically altered history, the great scientists and mathematicians, are seldom mentioned, if at all.

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 & 13 \\ 1 & 2 \end{bmatrix}$$

Martin Gardner

1914-2010 (American mathematician)

Warm-ups (1 pt each):

$$\vec{e}_1 \vec{e}_2^T = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$\vec{e}_2^T \vec{e}_1 = [0]$$

$$AA^{-1} = I$$

1.) (1 pt) According to Gardner (above), who should receive more focus in history classes?

Those who changed history thru science and math merit more attention.

2.) (8 pts) Consider the matrices

$$A = \begin{bmatrix} 4 & -3 & 2 \\ 2 & 0 & -1 \end{bmatrix}, B = \begin{bmatrix} -3 & -4 & 1 \\ 1 & -5 & 7 \end{bmatrix}, \text{ and } C = \begin{bmatrix} 1 & -2 \\ 3 & 4 \end{bmatrix}$$

Compute $A+2B$, BC , and CB . If an expression is undefined, explain why.

$$A + 2B = \begin{bmatrix} 4 & -3 & 2 \\ 2 & 0 & -1 \end{bmatrix} + 2 \begin{bmatrix} -3 & -4 & 1 \\ 1 & -5 & 7 \end{bmatrix} = \begin{bmatrix} -2 & -11 & 4 \\ 4 & -10 & 13 \end{bmatrix}$$

BC is undefined $(2 \times 3) \cdot (2 \times 2)$

↑
must match

$$CB = \begin{bmatrix} 1 & -2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} -3 & -4 & 1 \\ 1 & -5 & 7 \end{bmatrix} = \begin{bmatrix} -5 & 6 & -13 \\ -5 & -32 & 31 \end{bmatrix}$$

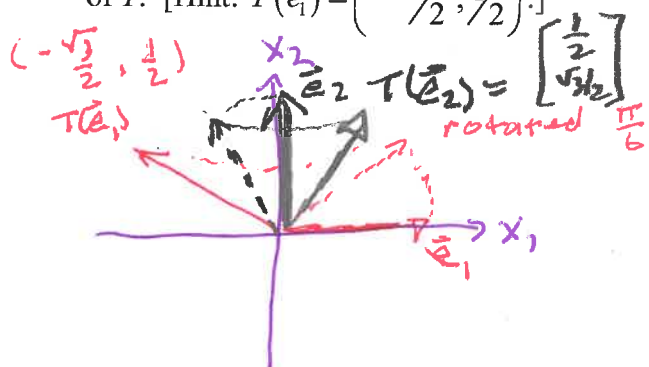
3.) (8 pts) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ first rotates points through $\pi/6$ radians and then reflects the points through the vertical x_2 -axis. Assume that T is a linear transformation. Find the standard matrix A .

of T . [Hint: $T(\vec{e}_1) = (-\sqrt{3}/2, 1/2)$.]

$$T(\vec{x}) = A\vec{x}$$

-1 if \uparrow

-2 no rotated thru x_1 -axis.



$$T(\vec{x}) = A\vec{x} \quad \text{w/} \quad A = \begin{bmatrix} T(\vec{e}_1) & T(\vec{e}_2) \\ | & | \\ | & | \end{bmatrix} \\ = \begin{bmatrix} -\sqrt{3}/2 & 1/2 \\ 1/2 & \sqrt{3}/2 \end{bmatrix}$$

4.) (8 pts) Use the **matrix inverse** to solve $A\vec{x} = \vec{b}$ where $A = \begin{bmatrix} 1 & 2 & -1 \\ -2 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} 4 \\ 1 \\ -1 \end{bmatrix}$.

$$[A|I] = \left[\begin{array}{ccc|ccc} 1 & 2 & -1 & 1 & 0 & 0 \\ -2 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 & 0 & 1 \end{array} \right]$$

-1 if A^{-1} (3×3)

-3 for $\begin{bmatrix} 7 \\ -9 \\ 3 \end{bmatrix}$

$$\sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 2 \\ 0 & 1 & 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 2 & 3 & 4 \end{array} \right]$$

$$= [I|A^{-1}]$$

$$\vec{x} = A^{-1}\vec{b} \Rightarrow \vec{x} = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & 1 \\ 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ 7 \end{bmatrix}$$

5.) (6 pts) True or False (circle one). Justify your answer.

- a.) (T or F) A linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is completely determined by its effect on the columns of the $n \times n$ identity matrix.

$$T(\vec{x}) = A\vec{x} \quad \text{where } A = \begin{bmatrix} | & & | \\ T(\vec{e}_1) & \dots & T(\vec{e}_n) \\ | & & | \end{bmatrix}$$

and $\vec{e}_1, \dots, \vec{e}_n$ are the cols of the $n \times n$ identity matrix.

- b.) (T or F) $(AB)^T = A^T B^T$

$$(AB)^T = B^T A^T$$

- c.) (T or F) If A and B are $n \times n$ and invertible then $A^{-1}B^{-1}$ is the inverse of AB .

$$(AB)^{-1} = B^{-1}A^{-1}$$

6.) (3 pts) Complete the following proof.

Claim: Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Then T is one-to-one if and only if the equation $T(\vec{x}) = \vec{0}$ has only the trivial solution.

Proof.

(\Rightarrow) Assume T is one-to-one.
 We know $T(\vec{0}) = \vec{0}$ (since T is a L.T.)
 $\Rightarrow T(\vec{x}) = \vec{0}$ has a solution and it must be unique since T is one-to-one.

(\Leftarrow) Assume $T(\vec{x}) = \vec{0}$ has only the trivial solution.
 Suppose T is not one-to-one,
 \Rightarrow there exists $\vec{u} \neq \vec{v} \in \mathbb{R}^n$ and $\vec{b} \in \mathbb{R}^m$
 such that $T(\vec{u}) = \vec{b}$ and $T(\vec{v}) = \vec{b}$
 $\Rightarrow T(\vec{u} - \vec{v}) = T(\vec{u}) - T(\vec{v}) = \vec{b} - \vec{b} = \vec{0}$
 but $T(\vec{x}) = \vec{0}$ has only the trivial soln so $\vec{u} = \vec{v}$,
 $\Rightarrow \Leftarrow$ (contradiction),
 $\Rightarrow T$ is one-to-one.

$\therefore T$ is one-to-one iff $T(\vec{x}) = \vec{0}$ has only the trivial solution.