

6.3 & 6.4: Orthogonal Projections & Gram-Schmidt

Math 220: Linear Algebra

Given a vector \mathbf{y} and a subspace W in \mathbb{R}^n there is a vector $\hat{\mathbf{y}} \in W$ such that

- 1) $\hat{\mathbf{y}}$ is the unique vector in W for which $\mathbf{y} - \hat{\mathbf{y}}$ is orthogonal to W
- 2) $\hat{\mathbf{y}}$ is the unique vector in W closest to \mathbf{y}

Theorem 8 The Orthogonal Decomposition Theorem

Let W be a subspace of \mathbb{R}^n . Then each \mathbf{y} in \mathbb{R}^n can be written uniquely in the form

$$\mathbf{y} = \hat{\mathbf{y}} + \mathbf{z} \quad (1)$$

where $\hat{\mathbf{y}}$ is in W and \mathbf{z} is in W^\perp . In fact, if $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is any orthogonal basis of W , then

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \dots + \frac{\mathbf{y} \cdot \mathbf{u}_p}{\mathbf{u}_p \cdot \mathbf{u}_p} \mathbf{u}_p \quad (2)$$

and $\mathbf{z} = \mathbf{y} - \hat{\mathbf{y}}$.

Ex 1: Let $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$. Write \mathbf{y} as the sum of a vector in W and a vector orthogonal to W .

$$\mathbf{y} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}, \mathbf{u}_1 = \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 5 \\ 1 \\ 4 \end{bmatrix}$$

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2$$

$$= \frac{0}{14} \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} + \frac{28}{42} \begin{bmatrix} 5 \\ 1 \\ 4 \end{bmatrix}$$

$$= \begin{bmatrix} 10/3 \\ 2/3 \\ 8/3 \end{bmatrix}$$

$$\therefore \mathbf{y} = \begin{bmatrix} 10/3 \\ 2/3 \\ 8/3 \end{bmatrix} + \begin{bmatrix} -7/3 \\ 7/3 \\ 7/3 \end{bmatrix}$$

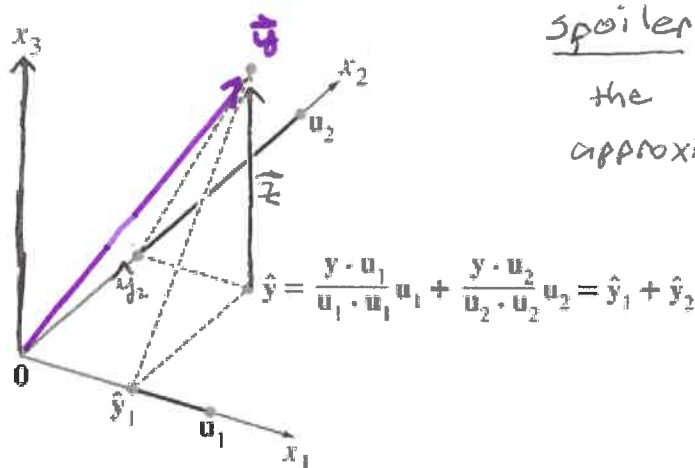
\uparrow vector in W \uparrow vector in W^\perp

$$\mathbf{z} = \mathbf{y} - \hat{\mathbf{y}}$$

$$= \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} - \begin{bmatrix} 10/3 \\ 2/3 \\ 8/3 \end{bmatrix}$$

$$= \begin{bmatrix} -7/3 \\ 7/3 \\ 7/3 \end{bmatrix}$$

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Spoiler: $\vec{y} \approx \hat{y}$ and the error in the approximation is \vec{z} .

Theorem 9 The Best Approximation Theorem

Let W be a subspace of \mathbb{R}^n , let y be any vector in \mathbb{R}^n , and let \hat{y} be the orthogonal projection of y onto W . Then \hat{y} is the closest point in W to y , in the sense that

$$\|y - \hat{y}\| < \|y - v\| \quad (3)$$

for all v in W distinct from \hat{y} .

Ex 2: As in Ex 1, $\begin{bmatrix} 10/3 \\ 2/3 \\ 8/3 \end{bmatrix}$ is the closest point in $W = \text{Span} \left\{ \mathbf{u}_1 = \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 5 \\ 1 \\ 4 \end{bmatrix} \right\}$ to $y = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$.

Find the distance from y to W

The distance from \vec{y} to $W = \|\vec{z}\|$

$$\begin{aligned} &= \sqrt{\frac{49}{9} + \frac{49}{9} + \frac{49}{9}} \\ &= \frac{7\sqrt{3}}{3} \end{aligned}$$

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Practice Problems

1. Let $\mathbf{u}_1 = \begin{bmatrix} -7 \\ 1 \\ 4 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix}$, $\mathbf{y} = \begin{bmatrix} -9 \\ 1 \\ 6 \end{bmatrix}$, and $W = \text{Span} \{\mathbf{u}_1, \mathbf{u}_2\}$.

Use the fact that \mathbf{u}_1 and \mathbf{u}_2 are orthogonal to compute $\text{proj}_W \mathbf{y}$.

$$\begin{aligned} \text{proj}_W \vec{y} &= \hat{y} \\ &= \frac{\vec{y} \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 + \frac{\vec{y} \cdot \vec{u}_2}{\vec{u}_2 \cdot \vec{u}_2} \vec{u}_2 \\ &= \frac{38}{66} \begin{bmatrix} -7 \\ 1 \\ 4 \end{bmatrix} + \frac{-2}{6} \begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix} \\ &= \begin{bmatrix} -9 \\ 1 \\ 6 \end{bmatrix} \end{aligned}$$

notice that $\hat{y} = \vec{y}$

which means $\vec{z} = \vec{0}$.

Phrased another way
 $\vec{y} \in W$

2. Let W be the subspace spanned by the \mathbf{u} 's, and write \mathbf{y} as the sum of a vector in W and a vector orthogonal to W .

$$\mathbf{y} = \begin{bmatrix} 4 \\ 3 \\ 3 \\ -1 \end{bmatrix}, \mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} -1 \\ 3 \\ 1 \\ -2 \end{bmatrix}, \mathbf{u}_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

$$\hat{y} = \frac{\vec{y} \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 + \frac{\vec{y} \cdot \vec{u}_2}{\vec{u}_2 \cdot \vec{u}_2} \vec{u}_2 + \frac{\vec{y} \cdot \vec{u}_3}{\vec{u}_3 \cdot \vec{u}_3} \vec{u}_3$$

$$= \frac{6}{3} \vec{u}_1 + \frac{10}{15} \vec{u}_2 + \frac{-2}{3} \vec{u}_3$$

$$= \begin{bmatrix} 2 & -2/3 & + 2/3 \\ 2 & + 2 & + 0 \\ 0 & + 2/3 & - 2/3 \\ 2 & - 4/3 & - 2/3 \end{bmatrix}$$

$$= \begin{bmatrix} 2 \\ 4 \\ 0 \\ 0 \end{bmatrix}$$

$$\vec{z} = \vec{y} - \hat{y} = \begin{bmatrix} 4 \\ 3 \\ 3 \\ -1 \end{bmatrix} - \begin{bmatrix} 2 \\ 4 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 3 \\ -1 \end{bmatrix}$$

$$\text{AND } \vec{y} = \begin{bmatrix} 4 \\ 3 \\ 3 \\ -1 \end{bmatrix} + \begin{bmatrix} 2 \\ -1 \\ 3 \\ -1 \end{bmatrix}$$

↑
vector
in W

↑
vector
in W^\perp

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The Gram-Schmidt Process

Ex 3: Let $W = \text{Span} \left\{ \overset{\text{Basis you are given}}{\mathbf{x}_1 = \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix}}, \mathbf{x}_2 = \begin{bmatrix} 8 \\ 5 \\ -6 \end{bmatrix} \right\}$, construct an **orthogonal basis** $\{\mathbf{v}_1, \mathbf{v}_2\}$. *Basis you want to find/construct*

$$\vec{v}_1 = \vec{x}_1$$

$$\vec{v}_2 = \vec{x}_2 - \hat{x}_2 \text{ where } \hat{x}_2 \text{ is the orthogonal projection of } \vec{x}_2 \text{ onto } \vec{v}_1$$

$$= \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \begin{bmatrix} 8 \\ 5 \\ -6 \end{bmatrix} - \frac{30}{10} \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix}$$

\therefore An **orthogonal basis** for W is:

Ex 4:

$$\text{Let } \mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \mathbf{x}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \text{ and } \mathbf{x}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}. \text{ Then } \{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3\} \text{ is}$$

clearly linearly independent and thus is a basis for a subspace W of \mathbb{R}^4 .

Construct an **orthogonal basis** for W . $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$

$$\vec{v}_1 = \vec{x}_1$$

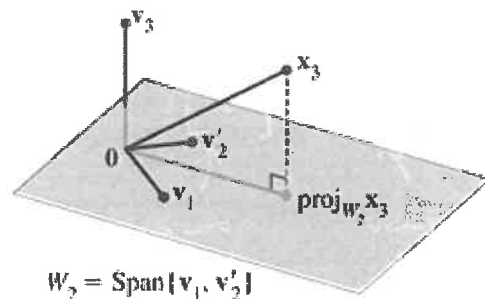
$$\vec{v}_2 = \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{3}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -3/4 \\ 1/4 \\ 1/4 \\ 1/4 \end{bmatrix}$$

key: use the given basis to iteratively construct an orthogonal basis.

$$\vec{v}_3 = \vec{x}_3 - \frac{\vec{x}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{x}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} - \frac{2}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{2/4}{12/16} \cdot \frac{1}{4} \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -2/3 \\ 1/3 \\ 1/3 \end{bmatrix}$$

\therefore An **orthogonal basis** for W is: $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{4} \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{3} \begin{bmatrix} 0 \\ -2 \\ 1 \\ 1 \end{bmatrix} \right\}$

Note: This orthogonal basis is **not unique** (the only orthogonal basis for W).



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Theorem 11 The Gram-Schmidt Process

Given a basis $\{\mathbf{x}_1, \dots, \mathbf{x}_p\}$ for a nonzero subspace W of \mathbb{R}^n , define

$$\begin{aligned} \mathbf{v}_1 &= \mathbf{x}_1 \\ \mathbf{v}_2 &= \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 \\ \mathbf{v}_3 &= \mathbf{x}_3 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 \\ &\vdots \\ \mathbf{v}_p &= \mathbf{x}_p - \frac{\mathbf{x}_p \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{x}_p \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 - \dots - \frac{\mathbf{x}_p \cdot \mathbf{v}_{p-1}}{\mathbf{v}_{p-1} \cdot \mathbf{v}_{p-1}} \mathbf{v}_{p-1} \end{aligned}$$

Then $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is an orthogonal basis for W . In addition

$$\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_k\} = \text{Span}\{\mathbf{x}_1, \dots, \mathbf{x}_k\} \quad \text{for } 1 \leq k \leq p$$

The result of this is that every nonzero subspace W in \mathbb{R}^n has an orthogonal basis.

An orthonormal basis is constructed easily by normalizing all the \mathbf{v}_k 's to unit vectors.

Ex 5: Re-write the orthogonal basis found in Ex 3 as an orthonormal basis.

The orthogonal basis we found was: $\left\{ \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 5 \\ -3 \end{bmatrix} \right\}$

$\vec{v}_1 \perp \vec{v}_2$ by construction. We just need to scale them to unit vectors.

$\|\vec{v}_1\| = \sqrt{10}$ and $\|\vec{v}_2\| = \sqrt{35}$, so an orthonormal basis is: $\left\{ \begin{bmatrix} 3/\sqrt{10} \\ 0 \\ -1/\sqrt{10} \end{bmatrix}, \begin{bmatrix} -1/\sqrt{35} \\ 5/\sqrt{35} \\ -3/\sqrt{35} \end{bmatrix} \right\}$

using the same method, an orthonormal basis for the space in ex 4 is:

$$\left\{ \frac{1}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{2\sqrt{2}} \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 0 \\ -2 \\ 1 \\ 1 \end{bmatrix} \right\}$$

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Practice Problems

1. Let $W = \text{Span}\{\mathbf{x}_1, \mathbf{x}_2\}$, where $\mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ and $\mathbf{x}_2 = \begin{bmatrix} 1/3 \\ 1/3 \\ -2/3 \end{bmatrix}$

orthogonal basis since $\frac{\mathbf{x}_1 \cdot \mathbf{x}_2}{\|\mathbf{x}_1\| \|\mathbf{x}_2\|} = 0$

Construct an orthonormal basis for W .

$$\|\vec{x}_1\| = \sqrt{3}$$

$$\|\vec{x}_2\| = \frac{\sqrt{6}}{3}$$

orthonormal basis

we can organize all this with

$$\left\{ \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \frac{3}{\sqrt{6}} \begin{bmatrix} 1/3 \\ 1/3 \\ -2/3 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 1 & 1/3 \\ 1 & 1/3 \\ 1 & -2/3 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{3} & 1/\sqrt{6} \\ 1/\sqrt{3} & 1/\sqrt{6} \\ 1/\sqrt{3} & -2/\sqrt{6} \end{bmatrix} \begin{bmatrix} \sqrt{3} & 0 \\ 0 & \sqrt{6}/3 \end{bmatrix}$$

A. Columns of A are linearly independent

Q. The columns of Q are an orthonormal basis for col A

R. R is an upper triangular matrix

2. Use the Gram-Schmidt process to produce an orthogonal basis for W .

$$W = \text{Span}\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3\} \text{ where } \mathbf{x}_1 = \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix}, \mathbf{x}_2 = \begin{bmatrix} 6 \\ -8 \\ -2 \\ -4 \end{bmatrix}, \mathbf{x}_3 = \begin{bmatrix} 6 \\ 3 \\ 6 \\ -3 \end{bmatrix}$$

$$\vec{v}_1 = \vec{x}_1 = \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} \text{ and } \|\vec{v}_1\| = \sqrt{12}$$

$$\vec{v}_2 = \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \begin{bmatrix} 6 \\ -8 \\ -2 \\ -4 \end{bmatrix} - \frac{-36}{12} \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix} \text{ and } \|\vec{v}_2\| = \sqrt{12}$$

$$\vec{v}_3 = \vec{x}_3 - \frac{\vec{x}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{x}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 = \begin{bmatrix} 6 \\ 3 \\ 6 \\ -3 \end{bmatrix} - \frac{6}{12} \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} - \frac{30}{12} \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ 3 \\ -1 \end{bmatrix} \text{ and } \|\vec{v}_3\| \text{ is } \sqrt{12}$$

This can be organized w/a QR Factorization.

$$\begin{bmatrix} -1 & 6 & 6 \\ 3 & -8 & 3 \\ 1 & -2 & 6 \\ 1 & -4 & -3 \end{bmatrix} = \begin{bmatrix} -1/\sqrt{12} & 2/\sqrt{12} & -1/\sqrt{12} \\ 3/\sqrt{12} & 1/\sqrt{12} & -1/\sqrt{12} \\ 1/\sqrt{12} & 1/\sqrt{12} & 3/\sqrt{12} \\ 1/\sqrt{12} & -1/\sqrt{12} & -1/\sqrt{12} \end{bmatrix} \begin{bmatrix} \sqrt{12} & -3\sqrt{12} & \frac{1}{2}\sqrt{12} \\ 0 & \sqrt{12} & \frac{1}{2}\sqrt{12} \\ 0 & 0 & \sqrt{12} \end{bmatrix}$$