Name: Key

Assessment 4

Math 220: Linear Algebra

<u>Instructions</u>: Please carefully complete these questions by hand. Be sure to show all work (this includes notating steps in row reduction in matrices that include a variable).

Should you choose to work these on scratch paper, please do not put more than one question on a page. Additional sheets of paper are acceptable. Write your name on every page. You can submit more pages, but Gradescope will not accept less pages than the original assignment.

Upload your solutions to Gradescope by 8 am on Monday (2/22). During your presentation time, you will be asked to explain your thought process and reasoning on a randomly assigned question. Late submissions (or resubmissions) are available thru 5 pm with a 5% penalty. Resubmission is helpful if you think you can gain 5% in the process.

Please make sure to sign up for your presentation slot. If you are unavailable for any of the times available, please send me a note in Slack and we will find a time that works for you.

https://docs.google.com/spreadsheets/d/1TE17S-z6oWrdejMbX5txwWX-JowaTFspdJ-7pCtpodY/edit?usp=sharing

Reminders: It is okay to collaborate with peers and use online resources. However, the final work should be your own and you should be prepared to present on each question.

(1.1) Let $A = \begin{bmatrix} -2 & -4 & -16 \\ 3 & 5 & 19 \\ 1 & 3 & 14 \end{bmatrix}$. Find the third column of A^{-1} without computing the other two columns. Explain how this works. (Give exact answers) $\begin{bmatrix} -2 & -4 & -16 & 0 \\ 3 & 5 & 19 & 0 \\ 1 & 3 & 14 & 11 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 2 & 2 \\ 0 & 1 & 0 & -5 & 3 \\ 0 & 0 & 1 & 11 \end{bmatrix}$ So the 3^{rd} col. of A^{-1} is $\begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}$ This works because solving $A \times = \vec{e}_3$ gives the 3^{rd} col of A^{-1} .

(1.2) Find the inverse of $A = \begin{bmatrix} 1 & -2 & 1 \\ -5 & 11 & -6 \\ -4 & -1 & 5 \end{bmatrix}$, if it exists. Use the algorithm for finding A^{-1} that

involves row reducing $[A \mid I]$. If A is invertible, explain why this means the columns of A are linearly independent.

(1.3) Let A and B be $n \times n$ matrices. Prove that if AB is invertible, so is B.

Use the proof structure taught in class, in the videos, and in the class notes.

and AB is invertible, then B is invertible.

proof.

Let A and B are as above.

AB is invertible

=> det (AB) =0

=> det(A) det (B) +0

= der(B) +0

=> B is invertible.

Q. E.D.

(1.4) Consider the linear transformation $T: \mathbb{R}^2 \to \mathbb{R}^2$ where $T(x_1, x_2) = (2x_1 - 7x_2, -2x_1 + 6x_2)$. Show that T is invertible and find a formula for T^{-1} . Your result should be in the same notation as the T provided.

$$T(\vec{x}) = A\vec{x} \quad \text{where} \quad A = \begin{bmatrix} 2 & -7 \\ -2 & b \end{bmatrix}$$

$$\Rightarrow A^{-1} = -\frac{1}{2} \begin{bmatrix} 6 & 7 \\ 2 & 2 \end{bmatrix} = \begin{bmatrix} -3 & -7/2 \\ -1 & -1 \end{bmatrix}$$

$$T^{-1}(X_1, X_2) = \langle -3X_1, X_2 \rangle$$

(1.5) By hand, compute
$$\begin{vmatrix} -1 & 3 & 6 & 0 \\ 4 & 5 & 3 & 0 \\ 4 & 4 & 6 & 8 \\ 4 & 2 & 4 & 4 \end{vmatrix}$$
 (Checking with a calculator is recommended).

Ts the a \$500 ateal matrix invertible? why large work.

 $\begin{vmatrix} -1 & 3 & 6 & 0 \\ 4 & 5 & 3 & 0 \\ 4 & 5 & 3 & 0 \\ 4 & 5 & 3 & 0 \end{vmatrix} = -8 \begin{vmatrix} -1 & 3 & 6 \\ 4 & 5 & 3 \\ 4 & 2 & 4 \end{vmatrix} + 4 \begin{vmatrix} -1 & 3 & 6 \\ 4 & 5 & 3 \\ 4 & 2 & 4 \end{vmatrix} + 4 \begin{vmatrix} -1 & 3 & 6 \\ 4 & 5 & 3 \\ 4 & 4 & 4 \end{vmatrix}$
 $= -9 \begin{bmatrix} -1 & 3 & 3 & 4 & 3 \\ 2 & 4 & 4 & 4 \end{bmatrix} + 6 \begin{bmatrix} 4 & 5 \\ 4 & 2 \end{bmatrix}$
 $= -9 \begin{bmatrix} -1 & 3 & 3 & 4 & 4 \\ 2 & 4 & 4 & 4 \end{bmatrix} + 6 \begin{bmatrix} 4 & 5 \\ 4 & 2 \end{bmatrix}$
 $= -9 \begin{bmatrix} -1 & 3 & 6 & 4 & 4 \\ 2 & 4 & 4 & 4 \end{bmatrix} + 6 \begin{bmatrix} 4 & 5 \\ 4 & 2 \end{bmatrix} + 4 \begin{bmatrix} -1 & 18 & -3(12) + 6(-47) \\ -1 & 4 & 6 & 4 \end{bmatrix}$

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since det of the associated matrix
is non-zero, the matrix is invertible

(1.6) <u>By hand</u>, compute $\det(B^3)$ where $B = \begin{bmatrix} 2 & 0 & 2 \\ 1 & 2 & 4 \\ 2 & 2 & 2 \end{bmatrix}$. (<u>Checking with a calculator is recommended</u>).

$$det(B^{3}) = [det(B)]^{3}$$

$$2 | 2 | 2 | -2 | 2 | 2 |$$

$$= [0 - 2(6)]^{3}$$

(1.7) Let H and K be subspaces of a vector space V. The intersection if H and K, written as $H \cap K$, is the set of $\vec{v} \in V$ that belong to both H and K. Prove that $H \cap K$ is a subspace of V.

Use the proof structure taught in class, in the videos, and in the class notes.

Give an example in \mathbb{R}^2 to show that the union of two subspaces is not, in general, a subspace.

claim: If H, K are subspaces of vector space V, then HAK is a subspace,

proof

Lex H, K, and V be as given above,

O O E H and O E K so O E HAK

- 2 suppose $\vec{u}, \vec{w} \in H \land k$ $\Rightarrow \vec{u} + \vec{w} \in H \quad \text{and} \quad \vec{u} + \vec{w} \in k$ $\Rightarrow u + w \in H \land k$
- 3 suppose the HAK and reR

 in the HAK and rick

 in the HAK

 is a subspace.

HUK is NOT generally a subspace tor example, let H = span([0]) and k = span([0]). [1] & HUK but is clearly the sum of vectors in HUK,

(1.8) The set of $M_{2\times 2}$ of all 2×2 matrices is a vector space, under the usual operations of addition of matrices and multiplication by real scalars. Prove that the set H of all matrices of the form $\begin{bmatrix} a & b \\ 0 & d \end{bmatrix}$ is (or isn't) a subspace of $M_{2\times 2}$.

Use the proof structure taught in class, in the videos, and in the class notes.

(1.9) Determine whether the vector
$$\begin{bmatrix} 2 \\ 3 \\ 1 \\ 0 \end{bmatrix}$$
 is in the column space of $A = \begin{bmatrix} -11 & 7 & 1 & 0 \\ -5 & 2 & 4 & 5 \\ 10 & -8 & 4 & 7 \\ 3 & -2 & 0 & 0 \end{bmatrix}$, the null

space of A, both, or neither. Explain/justify your reasoning.

col. space
$$\begin{bmatrix} A & \begin{vmatrix} 3 \\ 1 & \end{vmatrix} \\ A & \begin{vmatrix} 3 \\ 0 & \end{vmatrix} \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -2 & 0 & | & -4 \\ 0 & 1 & | & -3 & 0 & | & -6 \\ 0 & 0 & 0 & 0 & | & -1 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$$
the system is consistent $(A\vec{x} = \vec{v})$ so
$$\vec{v} \in col A.$$

$$A\overrightarrow{V} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad 50 \quad \overrightarrow{J} \in \text{NVII}(A)$$

(1.10) Let $T: V \to W$ be a linear transformation from a vector space V into a vector space W. Prove that the range of T is a subspace of W.

Use the proof structure taught in class, in the videos, and in the class notes.

proof.

3)
$$\vec{x} \in range(T)$$
 and $r \in \mathbb{R}$
 $\Rightarrow \exists \vec{a} \text{ s.t. } T(\vec{a}) = \vec{u}$
 $\Rightarrow T(r\vec{a}) = r T(\vec{a}) = r \vec{u} \in range(T)$