

## Line Integrals

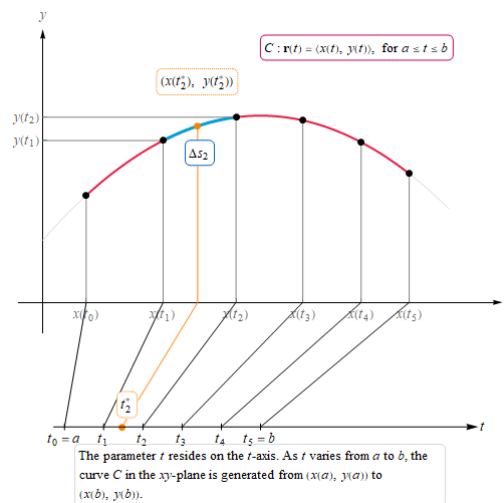
Objective:

1. Scalar line integrals in two and three dimensions
2. Line integrals across vector fields (work)
3. Circulation and flux

### I. Scalar line integrals in two and three dimensions

In previous chapters we considered three kinds of integrals in rectangular coordinates: single integrals over intervals, double integrals over two-dimensional regions, and triple integrals over three-dimensional regions. In this section we shall discuss line integrals, which are integrals over curves in two or three-dimensional space. Integrals over curves were invented/discovered in the early 19<sup>th</sup> century to solve problems involving a variety of things such as fluid flow, force, electricity, and magnetism. The application that is easiest to visualize is the surface area of the curtain “under” a surface and along a curve  $C$  on the  $xy$ -plane.

In order to unpack this surface area, we will need to parameterize the curve  $C$  which requires that we distinguish between the parameter  $t$  (not visible on the graph) and the arclength  $s$  (visible).

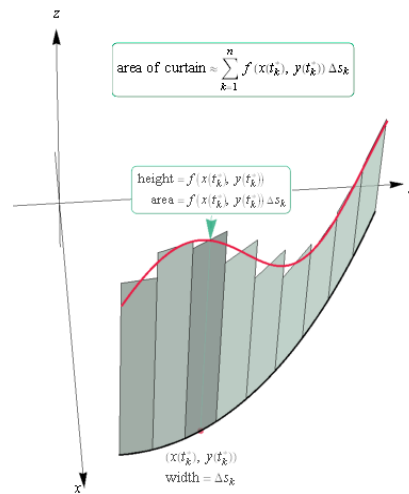


With this in mind, we can define and calculate the scalar line integral in the plane which represents that area of the curtain “under”  $f$  and above the  $xy$ -plane along the curve  $C$ .

**Definition:** Scalar Line Integral in the Plane

Suppose the scalar-valued function  $f$  is defined on a region containing the smooth curve  $C$  given by  $\vec{r}(t) = \langle x(t), y(t) \rangle$  for  $a \leq t \leq b$ .

The line integral of  $f$  over  $C$  is  $\int_C f(x(t), y(t)) ds = \lim_{\Delta t \rightarrow 0} \sum_{k=1}^n f(x(t_k^*), y(t_k^*)) \Delta s_k$  provided this limit exists over all partitions of  $[a, b]$ . When the limit exists,  $f$  is said to be integrable on  $C$ .



The key to applying this definition is finding a formula for  $ds$ . To do this, recall that if a space curve is parameterized by  $\vec{r}(t)$ , then the cumulative arclength of  $C$  over the interval  $[a, t]$  is  $s(t) = \int_a^t |\vec{r}'(u)| du$  which can be differentiated to reveal that  $s'(t) = |\vec{r}'(t)|$  or using Leibniz notation  $ds = |\vec{r}'(t)| dt$

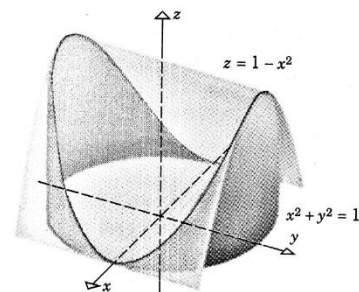
The punchline: To evaluate a scalar line integral “under”  $f$  and along the path  $C$  parameterized by  $\vec{r}(t)$  with  $a \leq t \leq b$ , we use the formulas:

$$\begin{aligned} \text{in } \mathbb{R}^2 : \int_C f ds &= \int_a^b f(x(t), y(t)) |\vec{r}'(t)| dt \\ &= \int_a^b f(x(t), y(t)) \sqrt{(x'(t))^2 + (y'(t))^2} dt \end{aligned}$$

and

$$\begin{aligned} \text{in } \mathbb{R}^3 : \int_C f ds &= \int_a^b f(x(t), y(t), z(t)) |\vec{r}'(t)| dt \\ &= \int_a^b f(x(t), y(t), z(t)) \sqrt{(x'(t))^2 + (y'(t))^2 + (z'(t))^2} dt \end{aligned}$$

**Ex1:** Find the area of the surface extending upward from the circle  $x^2 + y^2 = 1$  to the parabolic cylinder  $z = 1 - x^2$ .

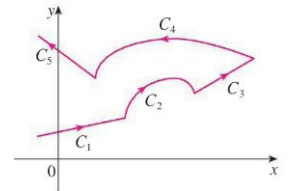


Important notes:

- The procedure for evaluating the line integral  $\int_C f \, ds$  (Formulas are given in two dimensions. The three dimensional versions are analogous).
  - Find a parametric description of  $C$  in the form  $\vec{r}(t) = \langle x(t), y(t) \rangle$  on  $a \leq t \leq b$
  - Compute  $|\vec{r}'(t)| = \sqrt{(x'(t))^2 + (y'(t))^2}$  which we need to find  $ds$ .
  - Make substitutions for  $x$  and  $y$  in the integrand and evaluate an ordinary integral:
 
$$\int_C f \, ds = \int_a^b f(x(t), y(t)) |\vec{r}'(t)| dt$$
- The value of the line integral doesn't depend on the parametrization of the curve, provided that the curve is traversed exactly once as  $t$  increases from  $a$  to  $b$ .
- Ordinary single integrals are a special case of the line integral where  $C$  is the line segment joining  $(a, 0)$  and  $(b, 0)$  with parametric equations  $x = x$   $y = 0$   $a \leq x \leq b$ . In this case the line integral formula simplifies from  $\int_C f(x, y) ds$  to  $\int_a^b f(x, 0) dx$

- If  $C$  is a **piecewise-smooth curve**, then we find the line integral for each piece and add them to get the line integral over  $C$ .

$$\int_C f(x, y) \, ds = \int_{C_1} f(x, y) \, ds + \int_{C_2} f(x, y) \, ds + \dots + \int_{C_n} f(x, y) \, ds$$



- Any physical interpretation of a line integral depends on the physical interpretation of the function  $f$ . For example, if  $f$  represents the density of a thin wire shaped like  $C$ , then the total mass is the line integral of  $f$  over  $C$ .
- When setting up a line integral, the most difficult step is parameterizing the curve  $C$ . Three common parameterizations are:
  - A line segment that starts with  $\vec{r}_0$  and ends in  $\vec{r}_1$  is given by:
 
$$\vec{r}(t) = (1-t)\vec{r}_0 + t\vec{r}_1 \quad 0 \leq t \leq 1$$
  - A circle ( $0 \leq t \leq 2\pi$ ) or a semicircle ( $0 \leq t \leq \pi$ ) centered at  $(x, y) = (a, b)$  with radius  $r$  is given by  $x = a + r \cos t$  and  $y = b + r \sin t$  for counter clockwise movement.
  - A curve that can be represented by a function  $y = f(x)$  on  $a \leq x \leq b$ . In this case we let  $x = t$  which makes  $y = f(t)$ . So  $\vec{r}(t) = \langle t, f(t) \rangle$  on  $a \leq t \leq b$ .

## II. Line integrals across vector fields (work)

This is what we have learned so far about work:

(review): Work Done by a Constant Force:

- If an object is moved a distance  $d$  in the direction of an applied constant force  $F$ , then the work  $W$  done by the force is defined as  $W = Fd$
- The work done by a constant force  $\vec{F}$  that moves an object from  $P$  to  $Q$  (creating displacement vector  $\vec{D}$ ) can be calculated by  $W = \vec{F} \cdot \vec{D}$

(review): Work Done by a Variable Force:

- If an object moves along a straight line from  $a$  to  $b$ , subject to a continuously varying force (not constant)  $f(x)$ , we define the work as  $W = \int_a^b f(x) dx$

(new): Work required to move a particle through a vector field:

- If an object moves along a smooth curve  $C$ , through a continuous force field  $\vec{F} = f(x, y)\vec{i} + g(x, y)\vec{j}$  defined on  $\mathbb{R}^2$ , then the work done is obtained by integrating the tangential component of force along the curve so  $W = \int_C \vec{F} \cdot \vec{T} ds$  where  $\vec{T}(x, y)$  is the unit tangent vector at the point  $(x, y)$  on  $C$ .

At first glance this looks complicated, but work is actually straight forward to implement. Recall

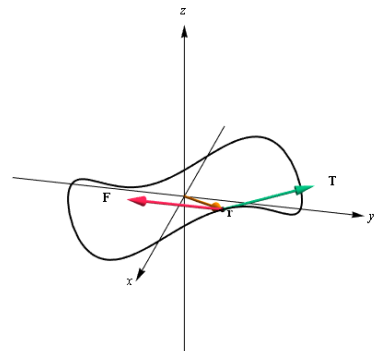
that if the curve is given by the vector equation  $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j}$ , then  $\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$ .

This means that we calculate work using the formula:

$$W = \int_C \vec{F} \cdot \vec{T} ds = \int_C \vec{F} \cdot \underbrace{\frac{\vec{r}'(t)}{|\vec{r}'(t)|}}_{\vec{T}} \underbrace{|\vec{r}'(t)|}_{ds} dt = \int_C \vec{F} \cdot d\vec{r}$$

Or simply work =  $\int_C \vec{F} \cdot d\vec{r}$

The definition in three dimensions is analogous.



Ex2: Find the work done by the force field  $\vec{F} = x^3 y \vec{i} + (x - y) \vec{j}$  on a particle that moves along the parabola  $y = x^2$  from  $(-2, 4)$  to  $(1, 1)$ .

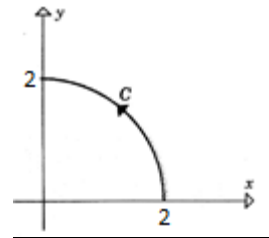
One common way to write the work formula is to reference  $x$ , and  $y$  rather than  $r$ . To do this, recall that

$\vec{r}(t) = \langle x(t), y(t) \rangle$ . This means that  $\frac{d\vec{r}}{dt} = \vec{r}'(t) = \langle x'(t), y'(t) \rangle$  and the work formula is:

$$\text{work} = \int_C \vec{F} \cdot d\vec{r} = \int_C \underbrace{\langle f(x, y), g(x, y) \rangle}_{\vec{F}} \cdot \underbrace{\langle x'(t), y'(t) \rangle}_{d\vec{r}} dt = \int_C f(x, y) dx + g(x, y) dy \quad \text{or simply}$$

$$\text{work} = \int_C \vec{F} \cdot d\vec{r} = \int_C f dx + g dy$$

**Ex3:** Evaluate the work  $= \int_C 2xy dx + (x^2 + y^2) dy$  required to move a particle along the circular arc  $C$ .



In general, the value of a line integral (and work) depends on three things:

- The location of the endpoints of the curve.
- The length and shape of the path (later will we learn conditions that cause the integral to be independent of path)
- The direction or orientation of the curve.

If  $-C$  denotes the curve consisting of the same points as  $C$  but with the opposite orientation (from initial point  $B$  to terminal point  $A$  in Figure 8), then we have

$$\int_{-C} f(x, y) dx = -\int_C f(x, y) dx \quad \int_{-C} f(x, y) dy = -\int_C f(x, y) dy$$

But if we integrate with respect to arc length, the value of the line integral does *not* change when we reverse the orientation of the curve:

$$\int_{-C} f(x, y) ds = \int_C f(x, y) ds$$

This is because  $\Delta s_i$  is always positive, whereas  $\Delta x_i$  and  $\Delta y_i$  change sign when we reverse the orientation of  $C$ .

**Ex4:** Evaluate the work  $= \int_C x^2 y dx + x dy$  for a particle to move in a counterclockwise direction around the triangular path given.

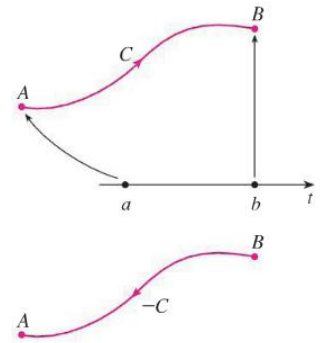
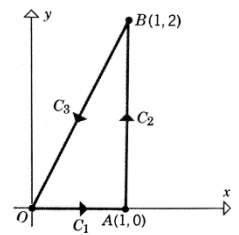


FIGURE 8





Ex5: Evaluate  $I = \int_C (xy + z^3) ds$  where  $C$  is the portion of the helix given by the parametric equations:

$$x = \cos t \quad y = \sin t \quad z = t \quad 0 \leq t \leq \pi$$

**Ex6:** Find the mass of a thin wire if the density function is  $\rho(x, y, z) = kz$  with  $k > 0$  and shaped in the form of a helix with parametric equations  $x = \cos t$   $y = \sin t$   $z = 2t$   $0 \leq t \leq \pi$ .

Ex7: Evaluate work =  $\int_C yz \, dx + xz \, dy + xy \, dz$  where  $C$  is  $\vec{r}(t) = t\vec{i} + t^2\vec{j} + t^3\vec{k}$  on  $0 \leq t \leq 1$ .

### III. Circulation and flux

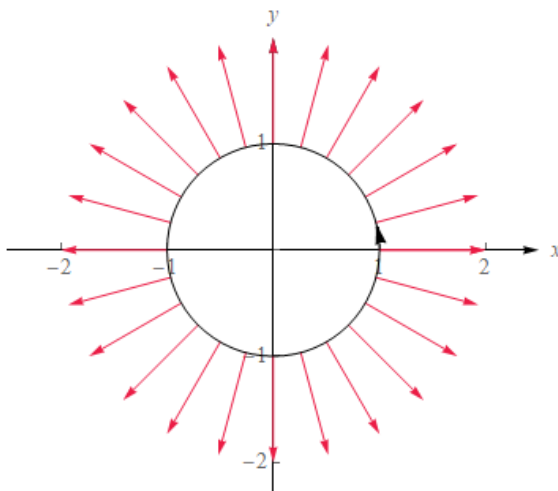
A number of the forthcoming theorems/results rely on the idea of a closed path (or closed curve). A closed curve is one whose initial and terminal points are the same.

In this case, we give the work to move an object around a closed path a new name: circulation.

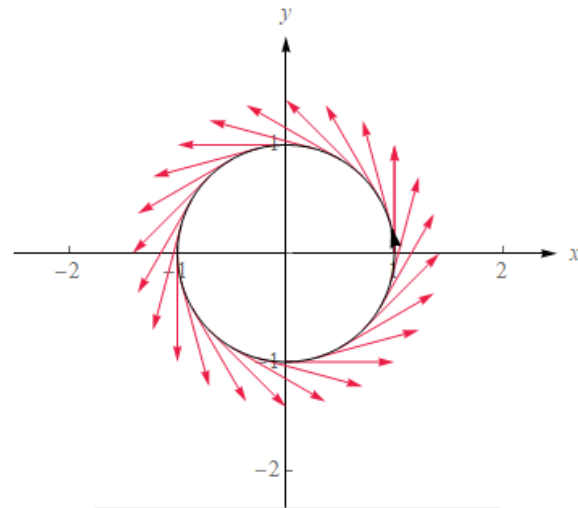
Definition: Circulation

Let  $\vec{F}$  be a continuous vector field on a region  $D$  of  $\mathbb{R}^3$  and let  $C$  be a closed smooth oriented curve in  $D$ . The circulation of  $\vec{F}$  is circulation = work =  $\oint_C \vec{F} \cdot \vec{T} ds$  where  $\oint$  represents the line integral around a closed path.

Ex8: Let  $C$  be the unit circle with counterclockwise orientation. Find the circulation on  $C$  for the radial flow field  $\vec{F} = \langle x, y \rangle$  and the rotation flow field  $\vec{F} = \langle -y, x \rangle$



On the unit circle,  $\mathbf{F} = \langle x, y \rangle$  is orthogonal to  $C$  and has zero circulation on  $C$ .

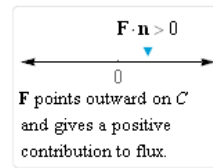
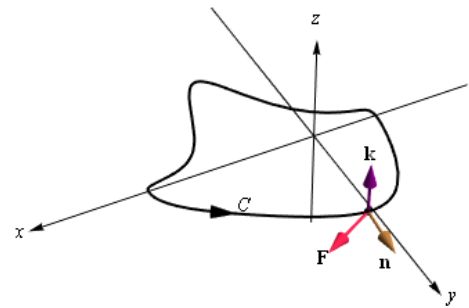


On the unit circle,  $\mathbf{F} = \langle -y, x \rangle$  is tangent to  $C$  and has positive circulation on  $C$ .

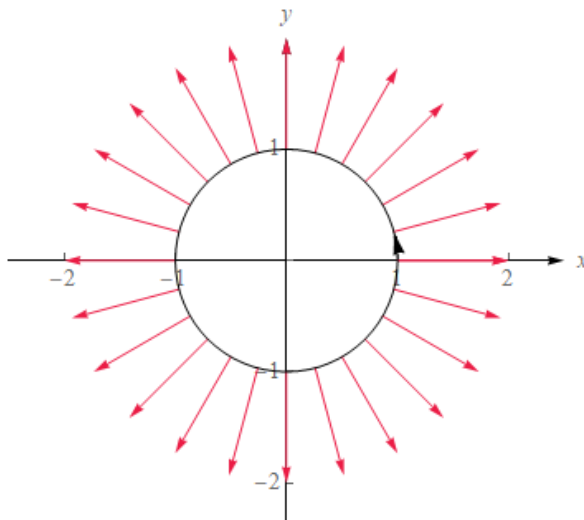
While circulation is a measure of the tangential component of field along a path, flux is a measure of the normal component of the field along a path.

In two dimensions, this will be  $\text{flux} = \int_C \vec{F} \cdot \vec{n} \, ds$  where

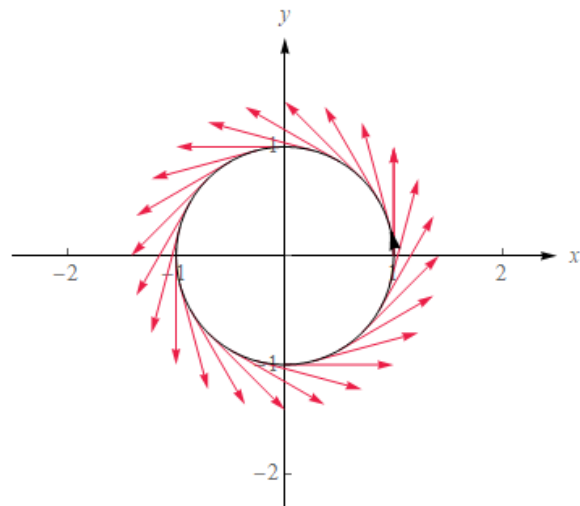
$\vec{n} = \vec{T} \times \vec{k}$  ( $\vec{k}$  being the unit vector in the  $z$  direction).



While we may not yet be able to calculate the flux, we already know enough to compare the flux and circulation in radial and rotational flows.



On the unit circle,  $\mathbf{F} = (x, y)$  is orthogonal to  $C$  and has positive outward flux on  $C$ .



On the unit circle,  $\mathbf{F} = (-y, x)$  is tangent to  $C$  and has zero outward flux on  $C$ .

**Ex9:** Derive the (computationally nice) formula for flux in two dimensions where  $\vec{F} = \langle f, g \rangle$  represents a continuous vector field traversed by path  $C: \vec{r}(t) = \langle x(t), y(t) \rangle$  for  $a \leq t \leq b$ .