

Test 3Dusty Wilson
Math 220**No work = no credit****No Calculators**Name: Key

Thus, the task is, not so much to see what no one has yet seen; but to think what nobody has yet thought, about that which everybody sees.

Erwin Rudolf Josef Alexander Schrödinger
1887 – 1961 (Austrian physicist)

$$\text{Warm-ups (1 pt each)}^1: \quad \bar{e}_1^T \bar{e}_1 = \underline{\quad} \quad -1^2 = \underline{-1} \quad \bar{e}_1 \bar{e}_1^T = \underline{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}$$

- 1.) (1 pt) According to Schrödinger, what is necessary to complete the task? (See above). Answer using complete English sentences.

The key is to have wherewithal to contemplate what is familiar & yet unknown.

- 2.) (10 pt) Find the eigenvalues of $A = \begin{bmatrix} 5 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 3 & 1 \\ 0 & 0 & -2 & 1 \end{bmatrix}$ and determine the stability of the zero state of the dynamical system $\bar{x}(t+1) = A\bar{x}(t)$.

$$\text{solve } \det(A - \lambda I) = 0$$

$$\Rightarrow 0 = (5-\lambda)(4-\lambda) \begin{vmatrix} 3-\lambda & 1 \\ -2 & 1-\lambda \end{vmatrix}$$

$$= (5-\lambda)(4-\lambda) \underbrace{[(3-\lambda)(1-\lambda) + 2]}_{3 - 4\lambda + \lambda^2 + 2}$$

$$= (5-\lambda)(4-\lambda)(\lambda^2 - 4\lambda + 5)$$

$$\lambda = 4, 5, \lambda = \frac{4 \pm \sqrt{16 - 4(1)(5)}}{2(1)}$$

$$= \frac{4 \pm \sqrt{-4}}{2}$$

$$= 2 \pm i$$

$|\lambda| > 1$ so

the system
is unstable

¹ In the warm-ups, \bar{e}_i refers to the standard basis vector in \mathbb{R}^2 .

Find the QR factorization of $A = \begin{bmatrix} 2 & 8 & 2 \\ 1 & 7 & -1 \\ -2 & -2 & 1 \end{bmatrix}$

$$\textcircled{1} \quad \vec{v}_1 = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$$

$$\|\vec{v}_1\| = 3 \quad \text{and} \quad \vec{u}_1 = \begin{bmatrix} 2/3 \\ 1/3 \\ -2/3 \end{bmatrix} \quad \text{step}$$

$$\textcircled{2} \quad \vec{v}_2^\perp = \vec{v}_2 - (\vec{v}_2 \cdot \vec{u}_1) \vec{u}_1 = \begin{bmatrix} 8 \\ 7 \\ -2 \end{bmatrix} - 9 \begin{bmatrix} 2/3 \\ 1/3 \\ -2/3 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 9 \end{bmatrix}$$

$$\|\vec{v}_2^\perp\| = \sqrt{4 + 16 + 81} = 6 \quad \text{and} \quad \vec{u}_2 = \begin{bmatrix} 1/3 \\ 2/3 \\ 2/3 \end{bmatrix} \quad \text{step}$$

$$\textcircled{3} \quad \vec{v}_3^\perp = \vec{v}_3 - (\vec{v}_3 \cdot \vec{u}_1) \vec{u}_1 - (\vec{v}_3 \cdot \vec{u}_2) \vec{u}_2$$

$$= \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 2/3 \\ 1/3 \\ -2/3 \end{bmatrix} - \frac{2}{3} \begin{bmatrix} 1/3 \\ 2/3 \\ 2/3 \end{bmatrix} = \begin{bmatrix} 14/9 \\ -14/9 \\ 7/9 \end{bmatrix}$$

$$\|\vec{v}_3^\perp\| = \sqrt{\frac{196}{81} + \frac{146}{81} + \frac{49}{81}} = \sqrt{\frac{441}{81}} = \frac{21}{9} = \frac{7}{3} \quad \text{and} \quad \vec{u}_3 = \begin{bmatrix} 2/3 \\ -2/3 \\ 1/3 \end{bmatrix}$$

$$A = \begin{bmatrix} 2/3 & 1/3 & 1/3 \\ 1/3 & 2/3 & -2/3 \\ -2/3 & 2/3 & 1/3 \end{bmatrix} \begin{bmatrix} 3 & 9 & 1/3 \\ 0 & 6 & 2/3 \\ 0 & 0 & 7/3 \end{bmatrix}$$

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the distribution vector

1.) (10 pts) The matrix $A = \begin{bmatrix} .5 & .25 \\ .5 & .75 \end{bmatrix}$ has eigenvalues 1 and 0.25. If $\vec{x}_0 = \begin{bmatrix} .7 \\ .3 \end{bmatrix}$, find $\lim_{t \rightarrow \infty} (A^t \vec{x}_0)$

$$E_1 = \text{span} \left(\begin{bmatrix} 1 \\ 2 \end{bmatrix} \right) \Rightarrow \vec{x}_{\text{eqv}} = \begin{bmatrix} \frac{\sqrt{3}}{2} \\ \frac{1}{2} \end{bmatrix}$$

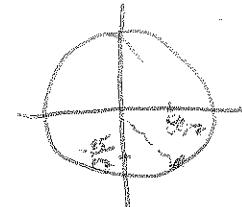
$$\Rightarrow \lim_{t \rightarrow \infty} A^t \vec{x}_0 = \vec{x}_{\text{eqv}} = \begin{bmatrix} \frac{\sqrt{3}}{2} \\ \frac{1}{2} \end{bmatrix}$$

2.) (10 pts) Consider the rotation-scaling matrix $B = \begin{bmatrix} 8 & 15 \\ -15 & 8 \end{bmatrix}$. Find the angle of rotation
→ 2. dijagonals
(degrees or radians) and the scaling factor.

$$B = 17 \begin{bmatrix} 8/17 & 15/17 \\ -15/17 & 8/17 \end{bmatrix}$$

$$\cos \theta = 8/17$$

$$\sin \theta = -15/17$$



$$\Rightarrow \tan \theta = -\frac{15}{8}$$

$$\Rightarrow \theta = \tan^{-1} \left(\frac{15}{8} \right)$$

$$\approx 61.41^\circ \text{ or } 1.07 \text{ rad.}$$

3.) (10 pts) Consider $A = \begin{bmatrix} 3 & 1 \\ -2 & 1 \end{bmatrix}$

a.) Find both eigenvectors for given that $\lambda_{1,2} = 2 \pm i$.

$$A - (2+i)\mathbb{I} \sim \begin{bmatrix} 1-i & 1 \\ -2 & -1-i \end{bmatrix} \xrightarrow{\text{Row } 2 + 2\text{Row } 1} \begin{bmatrix} 1-i & 1 \\ 0 & -3-i \end{bmatrix}$$

$$\xrightarrow{\text{Row } 2 + (-3-i)\text{Row } 1} \begin{bmatrix} 1-i & 1 \\ 0 & 0 \end{bmatrix} \quad 2R_1 + R_2 \rightarrow R_2$$

$$\xrightarrow{\text{Row } 2 + (-1-i)\text{Row } 1} \begin{bmatrix} 1-i & 1 \\ 0 & 0 \end{bmatrix}$$

Eigenvectors

so the roots
the two are

$$\begin{bmatrix} 1-i \\ 0 \end{bmatrix}, \begin{bmatrix} 1+i \\ 0 \end{bmatrix}$$

b.) Find an invertible matrix S such that $S^{-1}AS = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ where a and b are real numbers.

$$S = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} \quad \text{and} \quad S = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

4.) (10 pts) What are the similarities and differences between an orthonormal basis $\bar{u}_1, \dots, \bar{u}_m$ and an eigenbasis $\bar{v}_1, \dots, \bar{v}_m$ for a subspace V ?

similarities

- ① span ✓
- ② L.I.

differences

- ③ $\bar{u}_1, \dots, \bar{u}_m$ are orthonormal w/ length 1 while $\bar{v}_1, \dots, \bar{v}_m$ most likely are not.
- ④ $A\bar{v}_i = \lambda_i\bar{v}_i$ for $i=1, \dots, m$ while $A\bar{u}_i \neq \lambda_i\bar{u}_i$
for most $A \in \mathbb{R}^{n,n}$

5.) (9 pts) Answer the following. 1 point per problem is for an explanation/justification:

a.) If A_{nn} is diagonalizable (over \mathbb{R}), then there must be an eigenbasis for \mathbb{R}^n .

True since A is diagonalizable iff the # of L.I. is n (Thm 7.3.3).

b.) There exists a real 5×5 matrix without any real eigenvalues.

False, unless they come in conjugate pairs

c.) If α is an eigenvalue of A_{nn} and β is an eigenvalue of B_{nn} , then $\alpha\beta$ is an eigenvalue of AB .

False, unless A, B have the same dimension

6.) (10 pts) Find a real closed formula for the trajectory of $\bar{x}(t+1) = A^t \bar{x}(t)$, where

$$A = \begin{bmatrix} 1 & 5 \\ -2 & 7 \end{bmatrix} \text{ and } \bar{x}_0 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

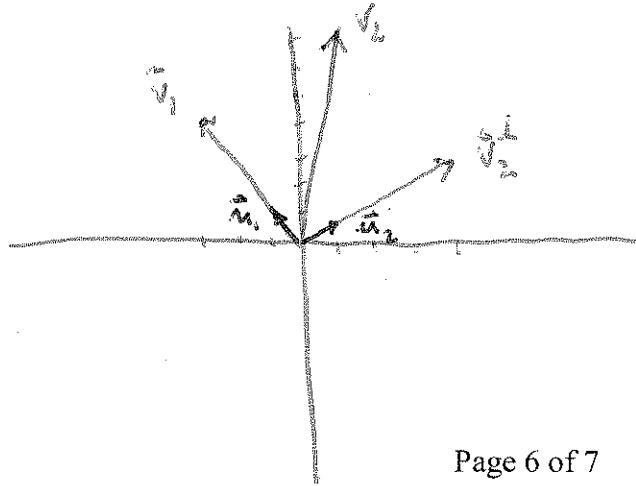
$$A \approx S B S^{-1} \text{ w/ } S = \begin{bmatrix} v_2 & v_1 \\ 0 & 1 \end{bmatrix} \text{ and } B = \begin{bmatrix} 4 & 1 \\ -1 & 4 \end{bmatrix}$$

CVT.

7.) (10 pts) Perform Gram-Schmidt orthogonalization on $\bar{v}_1 = \begin{bmatrix} -3 \\ 4 \end{bmatrix}$ and $\bar{v}_2 = \begin{bmatrix} 1 \\ 7 \end{bmatrix}$ and then illustrate your work with a sketch.

$$\hat{v}_1 = \begin{bmatrix} -3/\sqrt{5} \\ 4/\sqrt{5} \end{bmatrix}$$

$$\hat{v}_2 = \begin{bmatrix} 1 \\ 7 \end{bmatrix} - 5 \begin{bmatrix} -3/\sqrt{5} \\ 4/\sqrt{5} \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \end{bmatrix} \text{ and } \hat{v}_2 = \begin{bmatrix} 4/\sqrt{17} \\ 1/\sqrt{17} \end{bmatrix}$$



8.) (10 pts) Prove that for every vector $\vec{x} \in \mathbb{R}^n$ and a subspace V of \mathbb{R}^n we can write $\vec{x} = \vec{x}^{\parallel} + \vec{x}^{\perp}$ where \vec{x}^{\parallel} is in V and \vec{x}^{\perp} is perpendicular to V .

proof.

Let $\vec{x} \in \mathbb{R}^n$ and orthonormal basis $\vec{u}_1, \dots, \vec{u}_m$ for V be given.

If $\vec{x} = \vec{x}^{\parallel} + \vec{x}^{\perp}$, then there exist constants c_1, \dots, c_m

$$\text{s.t. } \vec{x}^{\parallel} = c_1 \vec{u}_1 + \dots + c_m \vec{u}_m$$

$$\Rightarrow \vec{x}^{\perp} = \vec{x} - \vec{x}^{\parallel}$$

$= \vec{x} - c_1 \vec{u}_1 - \dots - c_m \vec{u}_m$ is orthogonal to $\vec{u}_1, \dots, \vec{u}_m$

$$\Rightarrow \vec{u}_i \cdot \vec{x}^{\perp} = 0 \quad \text{for } i = 1, \dots, m$$

$$\Rightarrow 0 = \vec{u}_i \cdot (\vec{x} - c_1 \vec{u}_1 - \dots - c_m \vec{u}_m)$$

$$\Rightarrow c_i = \vec{u}_i \cdot \vec{x} \quad \text{for } i = 1, \dots, m$$

since these constants exist, we have a unique formula for \vec{x}^{\parallel} , \vec{x}^{\perp} , and \vec{x} .

Q.E.D.