

Four Special Subspaces

3.3

1/4

- (1) SPAN
- (2) NULL SPACE OR KERNEL
- (3) RANGE OR COLUMN SPACE
- (4) ROW SPACE.

Two ideas (one old & one new).

- (1) LINEAR TRANSFORMATION. IF $A_{m \times n}$ then $Ax = b$
- (2) LINEAR COMBINATION.

$$A: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

\vec{x} is a lin. comb of v_1, \dots, v_n
if $\exists a_1, \dots, a_n$ s.t.
 $\vec{x} = a_1v_1 + a_2v_2 + \dots + a_nv_n$.

(1) The Span

If $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m \in \mathbb{R}^n$ then the span of the vectors is the subspace $\text{sp}\{\vec{v}_1, \dots, \vec{v}_m\}$

Made up of all linear combinations of $\vec{v}_1, \dots, \vec{v}_m$

confirm it is a subspace.

(1) $0\vec{v}_1 + \dots + 0\vec{v}_m = \Theta$ is in the span $\Rightarrow \Theta$ is in the space.

(2) Take $x, y \in \text{span}$. $\Rightarrow x = a_1v_1 + a_2v_2 + \dots + a_nv_n$
and $y = b_1\vec{v}_1 + \dots + b_m\vec{v}_m$ for some a_i, b_i .
 $\Rightarrow x + y = (a_1 + b_1)v_1 + \dots + (a_n + b_n)v_n \in \text{span}$
since it is a lin. comb. of v_1, \dots, v_n .

(3) Take $x \in \text{span}$ & $a \in \mathbb{R}$

$$\Rightarrow ax = a(a_1v_1 + \dots + a_nv_n) = (aa_1)v_1 + \dots + (aa_n)v_n \in \text{span}.$$

Here $\text{sp}\{v_1, \dots, v_n\}$ is a subspace.

(2) The Null Space.

The null space of $A_{(m \times p)}$ (denoted $N(A)$)
is the set of all solutions to the homogeneous
eqt $Ax = \Theta$.

NOTE: $N(A) \subset \mathbb{R}^n$ (from the domain).

(1) The Θ is always a sol. to the homogeneous eqt.

(2) Suppose $x, y \in N(A)$.

$$\Rightarrow Ax = \Theta \quad \& \quad Ay = \Theta$$

$$\Rightarrow A(x + y) = Ax + Ay = \Theta + \Theta = \Theta$$

$$\Rightarrow x + y \in N(A)$$

(3) Suppose $x \in N(A) \quad \& \quad a \in \mathbb{R}$.

$$\Rightarrow Ax = \Theta$$

$$\Rightarrow A(ax) = a(Ax) = a\Theta = \Theta$$

$$\Rightarrow ax \in N(A).$$

Hence $N(A)$ is a subspace.

(3) The range or column space of A ($m \times n$) (denoted $R(A)$) is the set of vectors defined by:

$$R(A) = \{y \mid y = Ax \text{ for some } x \in \mathbb{R}^n\}.$$

NOTE: $R(A) \subset \mathbb{R}^m$ (from the range).

The range $R(A)$ is a subspace

- (1) if $x = 0$, then $Ax = 0 \Rightarrow 0 \in R(A)$.
- (2) suppose $y, z \in R(A) \Rightarrow \exists u, v \text{ s.t. } Au = y$ and $Av = z$.

$$\Rightarrow A(u+v) = Au + Av = y + z$$

~~$\exists x = u+v \text{ s.t. } Ax = y+z$~~

$$\Rightarrow \exists x = u+v \text{ s.t. } Ax = (y+z)$$

$$\Rightarrow y+z \in R(A).$$

- (3) suppose $y \in R(A)$ & $a \in \mathbb{R}$.

$$\Rightarrow \exists u \text{ s.t. } Au = y.$$

$$\Rightarrow A(au) = aAu = ay$$

$$\Rightarrow \exists x = au \text{ s.t. } Ax = ay$$

$$\Rightarrow ay \in R(A).$$

Hence $R(A)$ is a subspace.

Recall, if $A = [A_1, A_2, \dots, A_n]$, then

$$Ax = x_1 A_1 + x_2 A_2 + \dots + x_n A_n.$$

Thus the range is the linear combos of the columns ... hence the column space.

(4) The Row Space

3.3
48/4

If $A(m \times n)$ has rows $\vec{a}_1, \dots, \vec{a}_m$, then
the row space is $\text{sp}\{\vec{a}_1, \dots, \vec{a}_m\}$. It is equivalent
to the row space of any matrix row equiv. to A .