

Linear Independence & Non-singular Matrices

recall  $A = [A_1, A_2, \dots, A_n]$  and  $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$ , then

$$A\vec{x} = x_1 A_1 + x_2 A_2 + \dots + x_n A_n$$

we call this a linear combination of the vectors  $A_1, A_2, \dots, A_n$ .

So, we can write the eqn  $A\vec{x} = \vec{b}$  as  $x_1 A_1 + x_2 A_2 + \dots + x_n A_n = \vec{b}$

thus  $A\vec{x} = \vec{b}$  is consistent iff  $\vec{b}$  is a linear combo of the columns of  $A$ .

Ex 1: If the vectors  $A_1, A_2, A_3, \vec{b}_1$ , &  $\vec{b}_2$  are given by

$$A_1 = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix} \quad A_2 = \begin{bmatrix} 4 \\ 4 \\ 0 \end{bmatrix} \quad A_3 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \vec{b}_1 = \begin{bmatrix} 14 \\ 13 \\ -3 \end{bmatrix} \quad \vec{b}_2 = \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix}$$

$$A = [A_1, A_2, A_3]$$

solve  $[A | \vec{b}_1]$  and  $[A | \vec{b}_2] \rightarrow$  inconsistent.

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1/4 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} x_1 = 1 \\ x_2 = 3 - \frac{1}{4}x_3 \\ x_3 \text{ arbitrary} \end{array} \Rightarrow \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}$$

$$1A_1 + 2A_2 + 4A_3 = \vec{b}_1$$

Notation the zero vector is written

$$\vec{0} \text{ or } \Theta \text{ is } \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

so, the homogeneous eqt  $AX = \Theta$  can be written as  $x_1 A_1 + x_2 A_2 + \dots + x_n A_n = \Theta$

reminder the homogeneous eqt. always has the trivial solution  $X = \Theta$ .

Def: A set of  $n$ -dimensional vectors  $\{v_1, v_2, \dots, v_n\}$  is said to be linearly independent if the only solution to  $a_1 v_1 + a_2 v_2 + \dots + a_n v_n = \Theta$  is the trivial solution  $a_1 = a_2 = \dots = a_n = 0$ . The set is linearly dependent if it is not linearly ind.

That is,  $a_1 v_1 + a_2 v_2 + \dots + a_n v_n = \Theta$  has a non-trivial solution.

ex 2: Determine if  $v_1 = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$   $v_2 = \begin{bmatrix} 4 \\ 4 \\ 0 \end{bmatrix}$   $v_3 = \begin{bmatrix} 8 \\ 5 \\ -6 \end{bmatrix}$  are linearly independent.

$$\text{rref} \left( \begin{bmatrix} 2 & 4 & 8 & 0 \\ 1 & 4 & 5 & 0 \\ -3 & 0 & -6 & 0 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = -2x_3; \quad x_2 = -x_3; \quad x_3 \text{ arbitrary.}$$

If  $x_3 = 5$  (our choice),  $x_1 = -10$  &  $x_2 = -5$ .

$$\text{and } -10v_1 - 5v_2 + 5v_3 = \Theta \text{ (a non-trivial solution)}$$

Therefore, the vectors are linearly dependent.

ex 2 rev: If  $v_3 = \begin{bmatrix} 8 \\ 6 \\ 0 \end{bmatrix}$ , then the vectors are L.I.,  
( $\text{rref}([v_1, v_2, v_3 | 0]) = [I | 0]$ ).

Note: vectors are linearly dependent iff one vec. is a linear comb. of the remaining ones.

Notation: Unit vectors in  $\mathbb{R}^N$  are written as

$$e_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \leftarrow i^{\text{th}} \text{ position.}$$

Is it obvious that  $\{e_1, e_2, \dots, e_N\}$  is a L.I. set?

ex 3: show  $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 5 \\ 6 \end{bmatrix} \right\}$  are linearly dependent. (Simple because it is 2 eqs & 3 unknowns, so the homogeneous system has non-trivial solutions).

Thm: A set of vectors that includes more vectors than entries w/ the vectors is linearly dependent. (Too many vectors).

note: less vectors than dimensions does not guarantee L.I.

Reminder: only  $(n \times n)$  systems can have a unique solution.

Defn. An  $(n \times n)$  matrix  $A$  is nonsingular if  $Ax = \theta$  has only the trivial solution. Otherwise  $A$  is singular.

Thm: The  $(n \times n)$  matrix  $A = [A_1, A_2, \dots, A_n]$  is nonsingular iff  $\{A_1, A_2, \dots, A_n\}$  is a LI set.

ex 4: Determine whether the matrices are <sup>non</sup>singular.

(a)  $\begin{bmatrix} 4 & 7 \\ 3 & 2 \end{bmatrix}$

(b)  $\begin{bmatrix} 4 & 7 \\ -8 & -14 \end{bmatrix}$

Thm: Let  $A$  be an  $(n \times n)$  matrix. The eqn  $Ax = b$  has a unique sol iff  $A$  is nonsingular, for every  $b$ .  
proof

$(\Rightarrow)$  Suppose  $Ax = b$  has a unique sol. for all  $b$ . Take  $b = \theta$ .  $Ax = \theta$  has a unique sol. Therefore  $A$  is nonsingular.

$(\Leftarrow)$  Suppose  $A$  is nonsingular.  $\forall b$  any  $(n \times 1)$  col. vec.

(a) Show  $Ax = b$  has a sol.

$\{A_1, A_2, \dots, A_n, b\}$  is linearly dependent because there are too many vecs.

$\Rightarrow a_1 A_1 + a_2 A_2 + \dots + a_n A_n + a_{n+1} b = \theta$  has a non-trivial sol. if  $a_{n+1} = 0 \Rightarrow A$  is singular (contradiction), therefore  $a_{n+1} \neq 0$ .

Thm: Let  $A$  be an  $(n \times n)$  matrix. The equation  $Ax = b$  has a unique solution for every  $b$  iff  $A$  is nonsingular.

□ proof.

( $\Rightarrow$ ): Suppose  $Ax = b$  has a unique solution for every  $b$ . Then it must have a unique solution when  $b = \theta$ . ~~that is~~ Then  $Ax = \theta$  has only the trivial solution &  $A$  is nonsingular.

( $\Leftarrow$ ): Suppose  $A$  is nonsingular.

Part 1: Show  $Ax = b$  has a solution and so is consistent.

consider  $\{A_1, A_2, \dots, A_n, b\}$ . The set is linearly dependent by the "Too many vectors thm."

\*  $\Rightarrow a_1 A_1 + a_2 A_2 + \dots + a_n A_n + a_{n+1} b = \theta$  has a nontrivial solution

consider  $a_{n+1}$  in particular. It is either zero or nonzero. ~~supp~~ let's see if it is zero. (suppose  $a_{n+1} = 0$ ).

$\Rightarrow a_1 A_1 + a_2 A_2 + \dots + a_n A_n = \theta$  has a nontrivial solution which means  $A$  is singular  $\Rightarrow \Leftarrow$

so  $a_{n+1} \neq 0$  and solve (\*) for  $b$ .

$$\underbrace{-\frac{a_1}{a_{n+1}} A_1}_{S_1} + \underbrace{-\frac{a_2}{a_{n+1}} A_2}_{S_2} + \dots + \underbrace{-\frac{a_n}{a_{n+1}} A_n}_{S_n} = b.$$

$$\Rightarrow s_1 A_1 + s_2 A_2 + \dots + s_n A_n = b$$

Thus  $Ax = b$  has a solution  $s$  given by

$$s = [s_1, s_2, \dots, s_n]^T$$

so  $Ax = b$  has a solution & is consistent when  $A$  is nonsingular.

Part 2: The solution to  $Ax = b$  is unique (our claim)

We have one solution  $s$  to  $Ax = b$ . Suppose  $u$  ( $u \neq s$ ) is also a solution to  $Ax = b$ .

$$\Rightarrow As = b \text{ and } Au = b$$

$$\Rightarrow As - Au = b - b$$

$$\Rightarrow A(s - u) = 0$$

But  $A$  is nonsingular, so  $Ax = 0$  has only the trivial solution  $x = 0$ .

$$\Rightarrow s - u = 0 \text{ and } s = u.$$

Therefore, our solution is unique.  $\blacksquare$